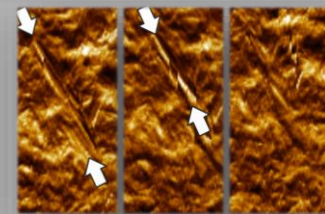
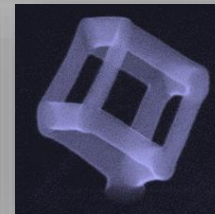
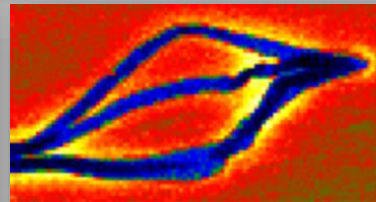
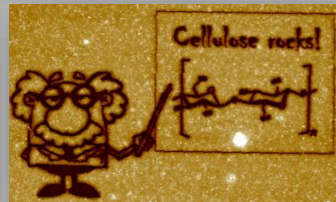


# Micromechanics

Ass.Prof. Priv.-Doz. DI Dr. Harald Plank <sup>a,b</sup>

<sup>a</sup> Institute of Electron Microscopy and Nanoanalysis, Graz University of Technology, 8010 Graz, AUSTRIA

<sup>b</sup> Graz Centre for Electron Microscopy, 8010 Graz, AUSTRIA

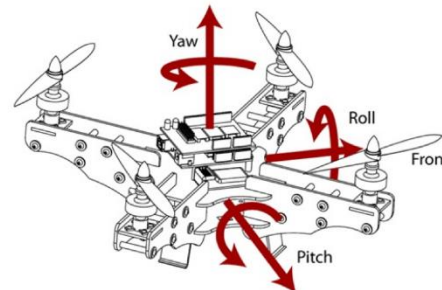
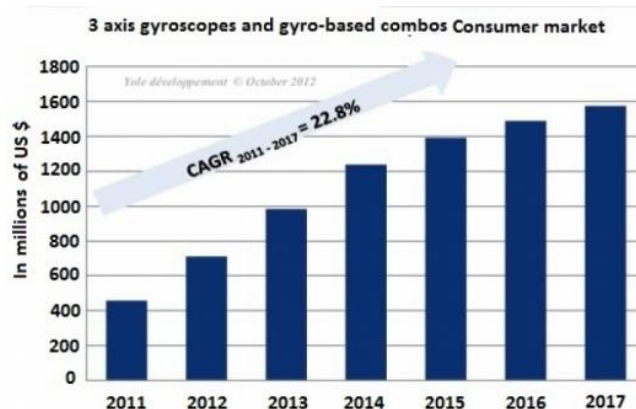
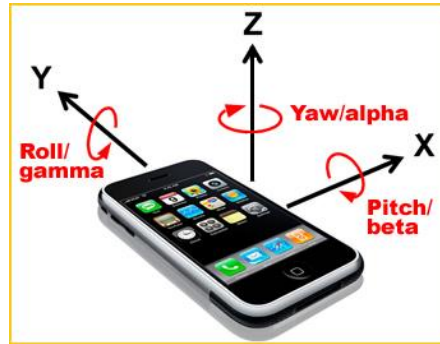
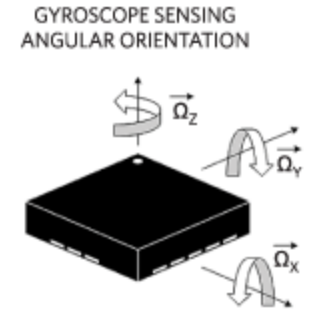
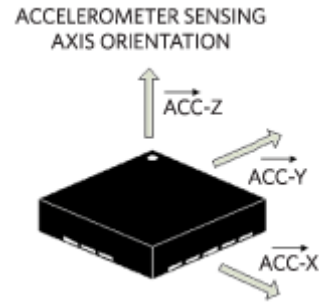


# APPLICATIONS – PART II

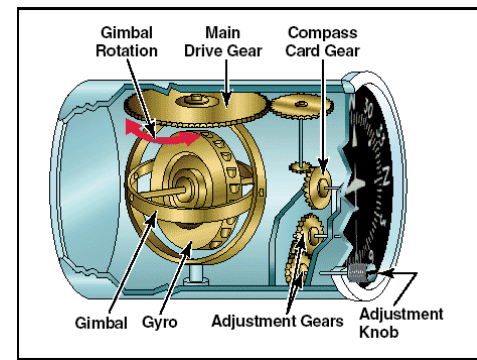


# Gyroscopes - Purpose

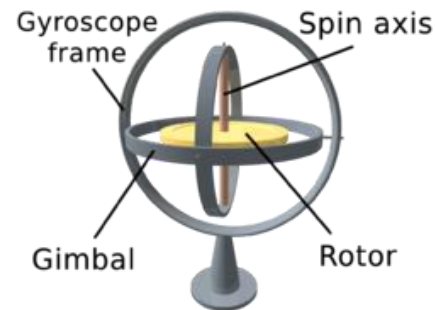
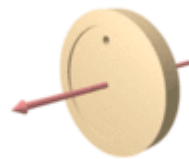
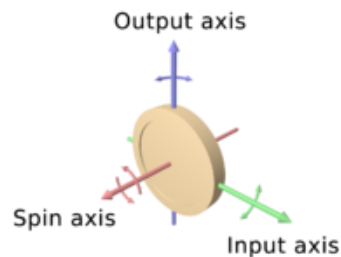
- So far, we **have discussed accelerometers** which gives information about the **spatial movements**
- A **gyroscope** is a device which gives information about the **spatial inclination of a system**
- By that it **complements classical accelerometers to give complete information about spatial inclination and movements**



# Gyroscopes – Function (Rotationally)



- In the past, gyroscopes used a **rotational approach**
- It bases on the **conservation of the angular momentum**
  - We start with a **central spin axis** which defines the angular momentum to be maintained
  - This is **placed in a detection and a frame gimbal**
  - Once a **force is applied** there is a **response perpendicular to the gimbal and spin axis**
  - By **smart integration** the **outer frame can be used as mechanical transducer**

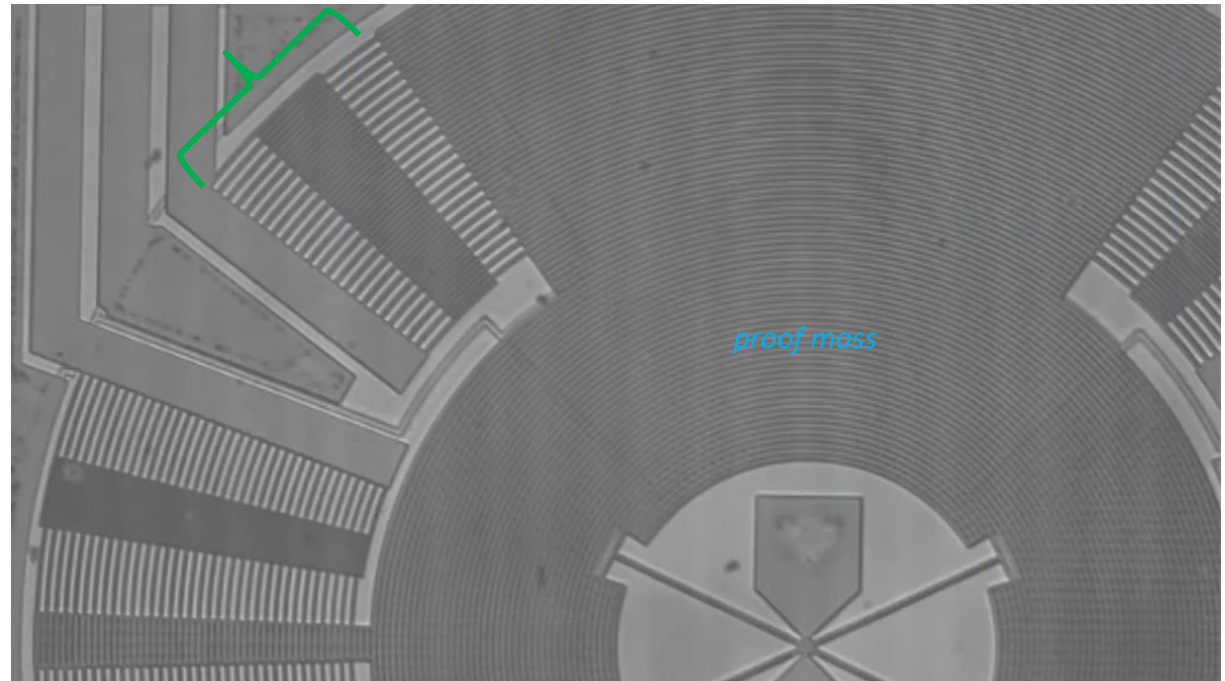


- State of the art **rotation gyroscopes** were about **2.5 cm large**, about **85 g light** and reached **rotation speeds of about 24.000 rpm**
- However, they **need to be highly balanced**, had **high demands on the bearings** and **were shock sensitive** → they were **replaced by simpler approaches** → **MEMS resonant gyroscopes!**

# Gyroscopes – Function (Vibratory)

- In **MEMS gyroscopes**, most concepts base on the **high-frequency oscillation** of the proof mass
- This **represents the angular momentum** to be maintained **caused by a drive voltage**
- When a spatial tilting event takes place, the **Coriolis force induces a perpendicular movement**
- This, in turn, **induces a capacitor change** which can be detected

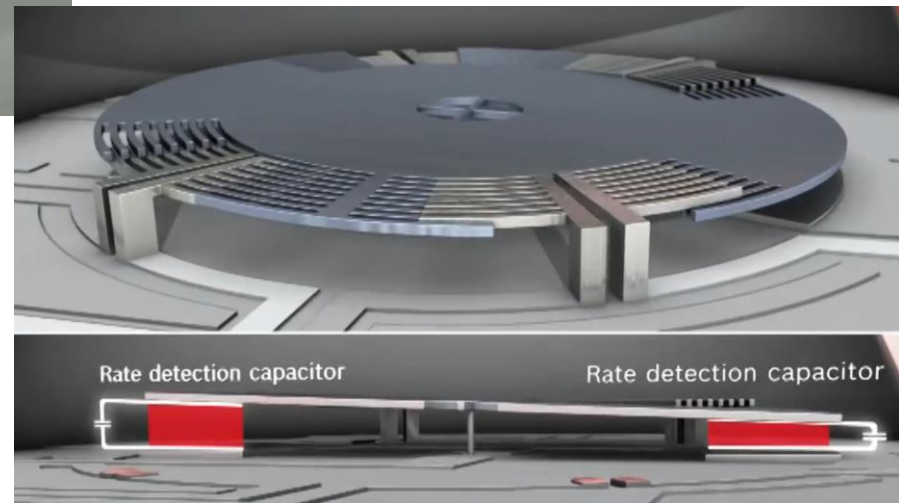
*capacitive detection  
element*



*drive voltage induces  
the rotational vibration*

# Gyroscopes – Function (Vibratory)

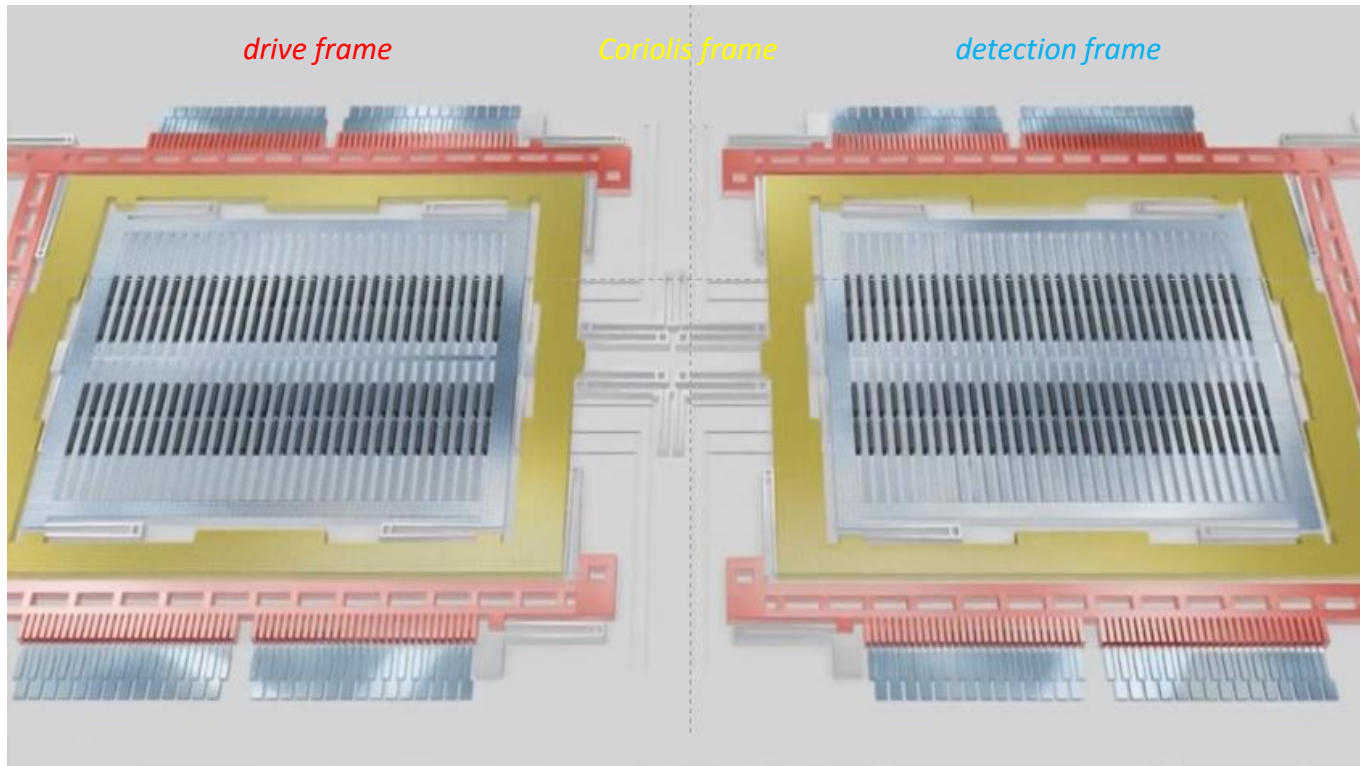
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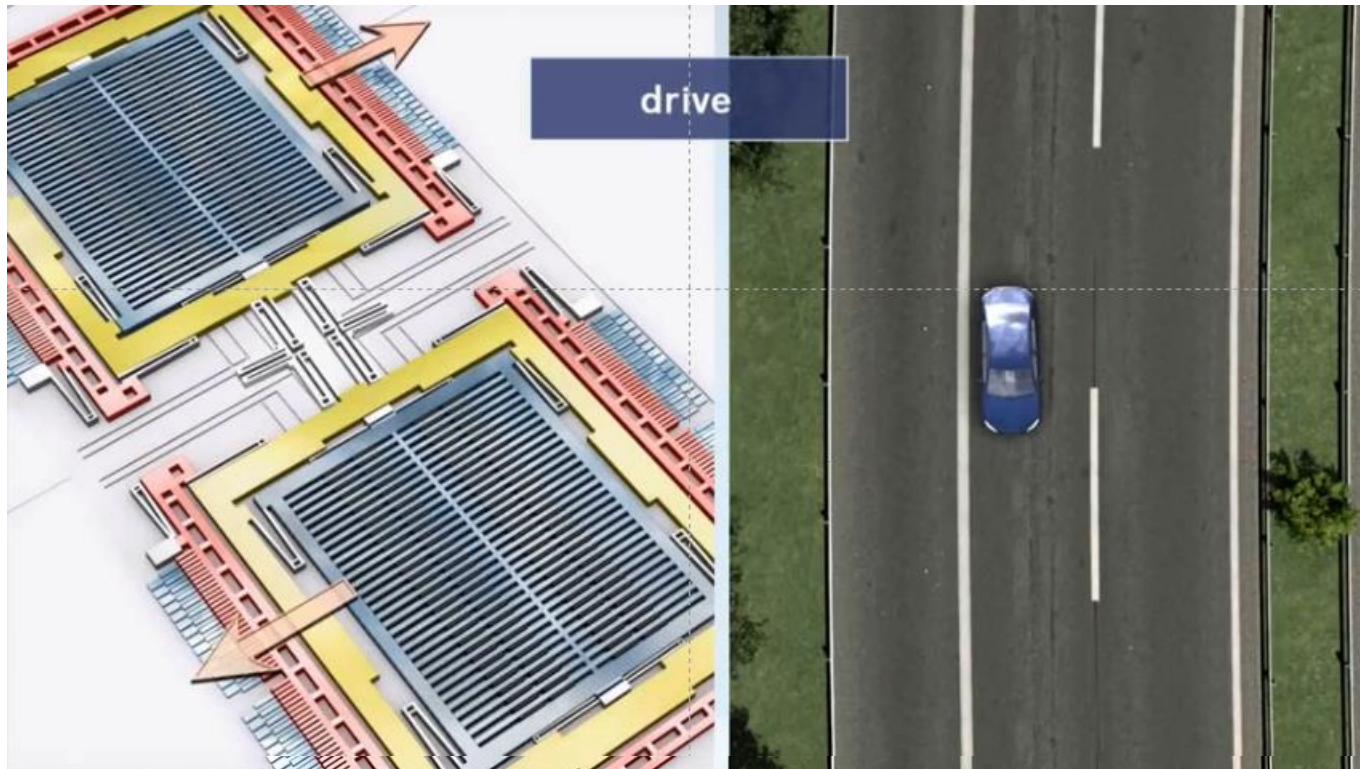
# Gyroscopes - Function

- As such “twisting” gyroscopes can be tricky in fabrication and operation due to very high precision demands, different more planar architectures have been developed



# Gyroscopes - Function

- As such “twisting” gyroscopes can be tricky in fabrication and operation due to very high precision demands, different more planar architectures have been developed



*drive frame*

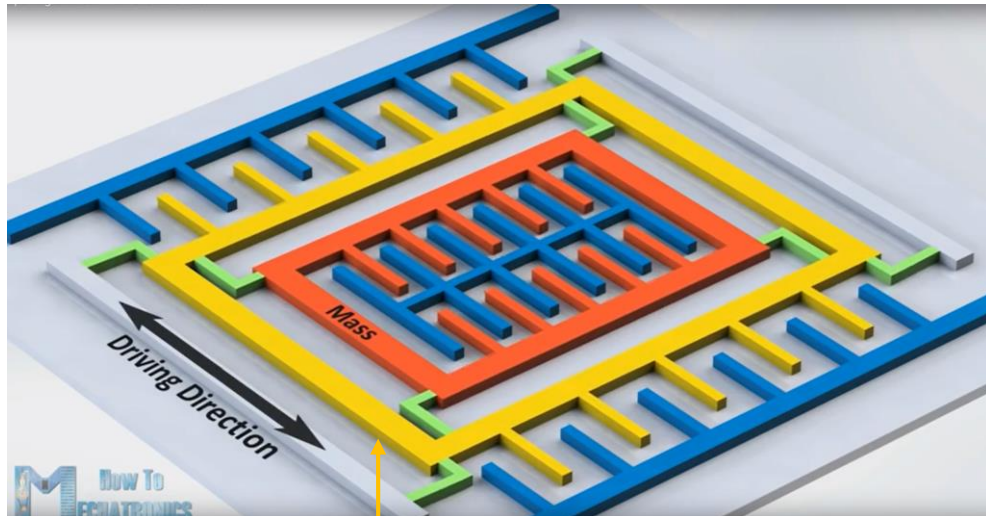
*Coriolis frame*

*detection frame*

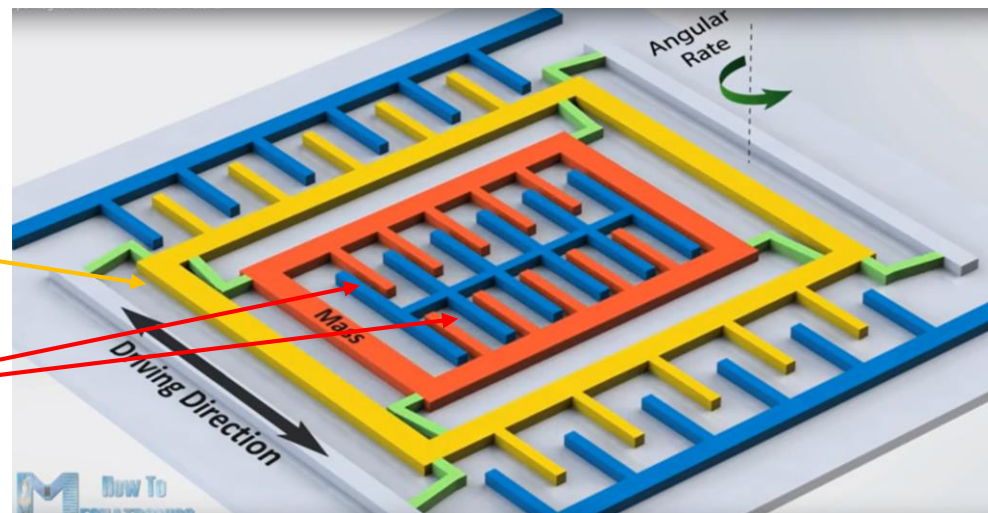


# Gyroscopes - Function

- The **basic detection element** is again **capacitive** as for the accelerometer



*drive voltage induces the horizontal oscillation*



*resonant frame*

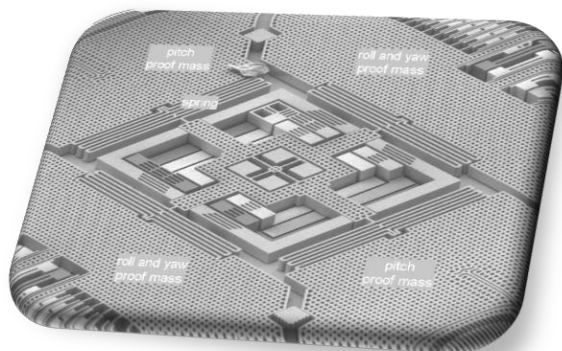
*Proof mass induces a  $\Delta C$*

# Gyroscopes - Function

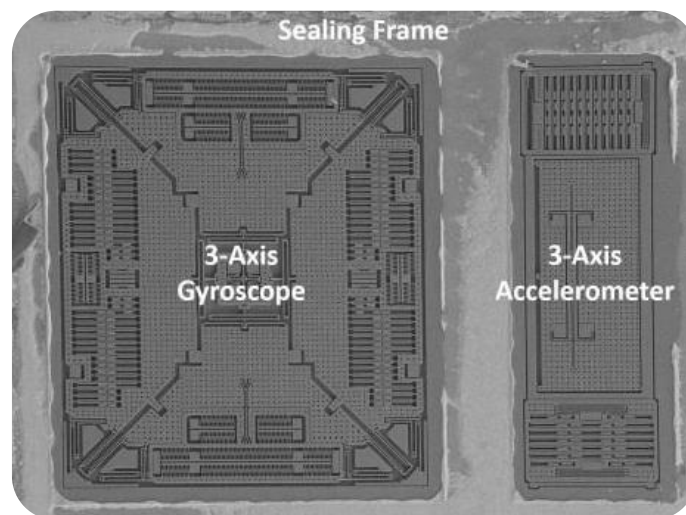
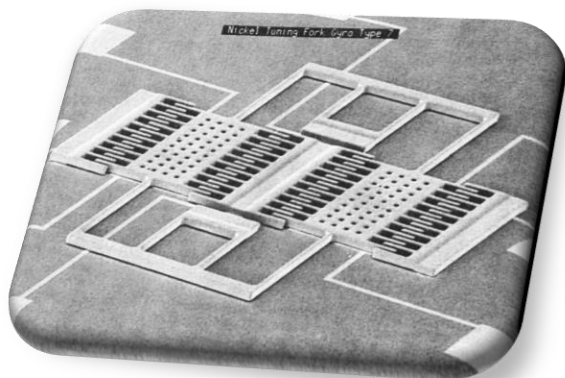
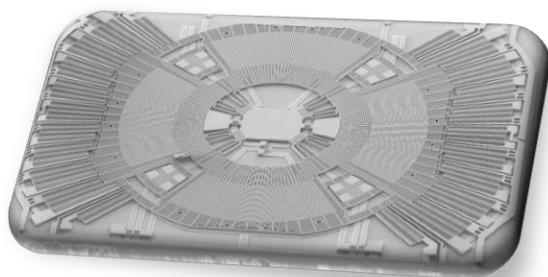
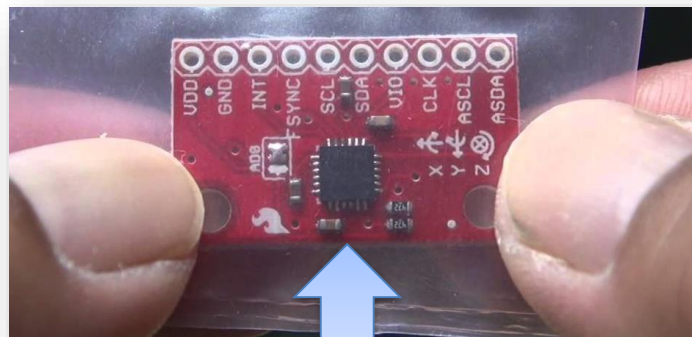
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# Gyroscopes – Many Different Types & Small Scale

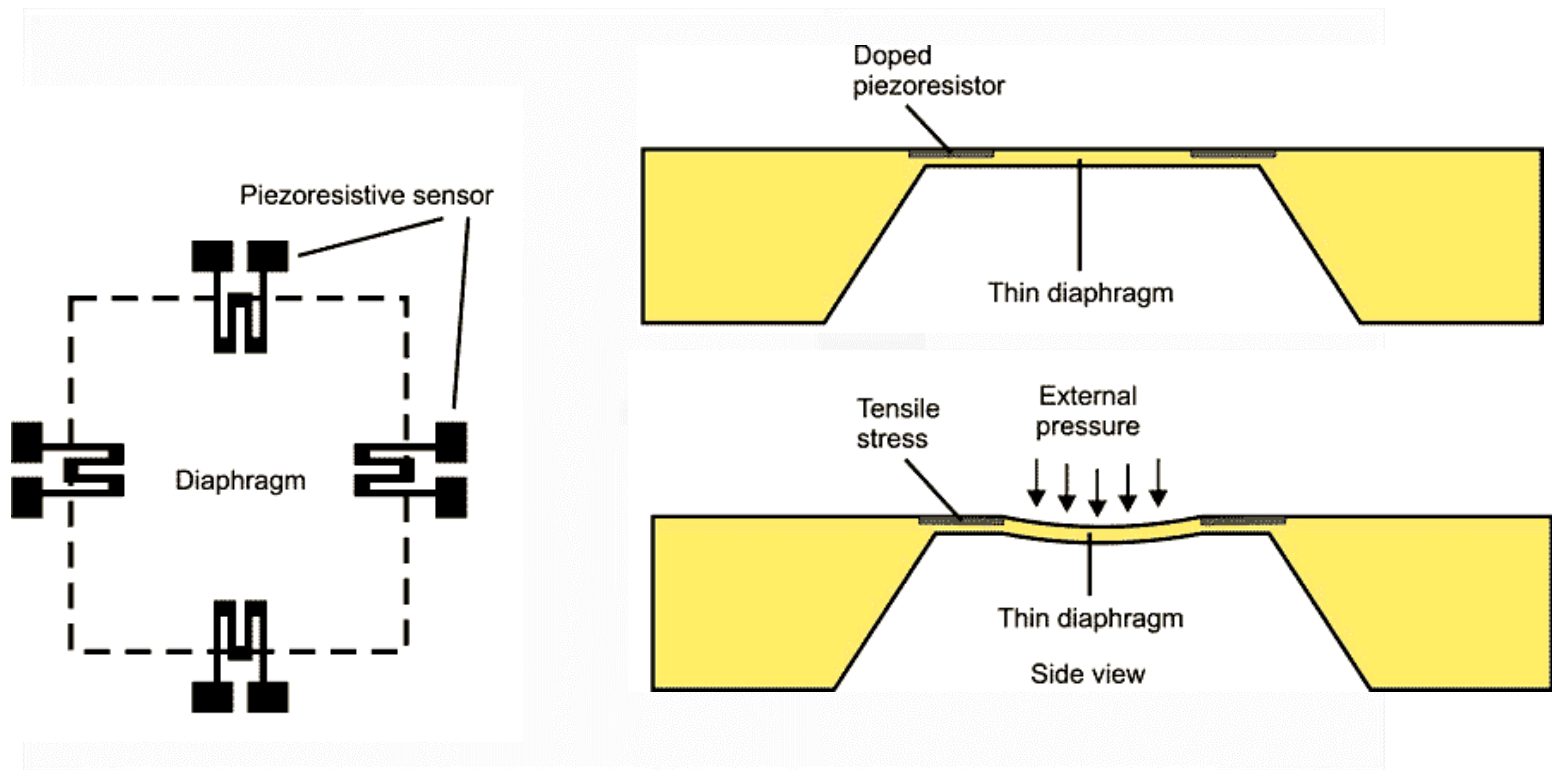


*fully operational 6 axes system including the required electronics*



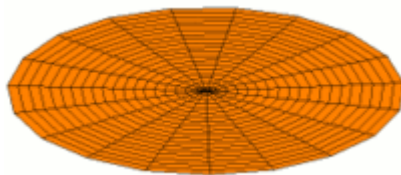
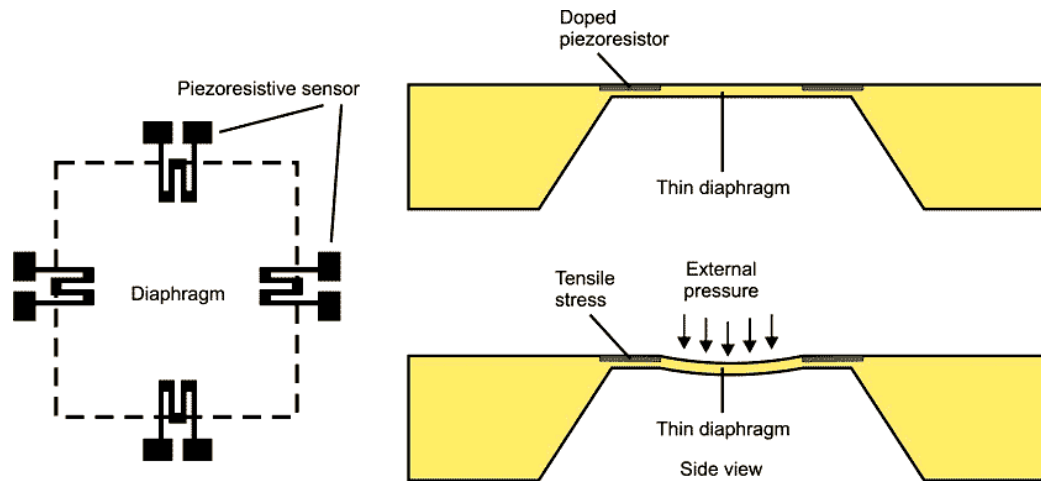
# Further Applications – Pressure MEMS

- To detect **pressure differences**, a **thin but flexible membrane** is used
- For this **piezoelectric (active)** OR **piezo-resistive (passive)** elements are strategically **integrated in the membrane**
- The **electric readout** gives then information about the **bending strength** and by that about the **quantitative pressure difference** between the upper and lower membrane face

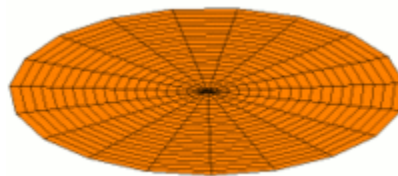


# Further Applications – MEMS Microphones

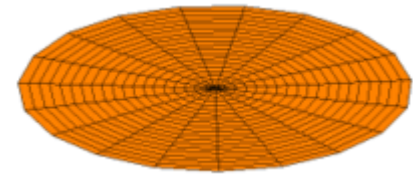
- This **basic principle** can also be used for **microphone applications**
- However, the **full frequency band can induce different membrane movements and / or higher harmonics excitations**
- For **silent noises** the membrane amplitude might be too small for proper piezo based detection



*basic frequency  
detection OK*



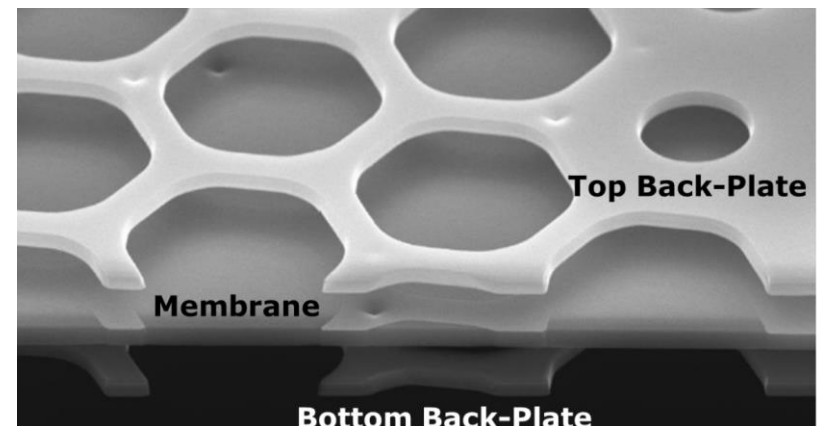
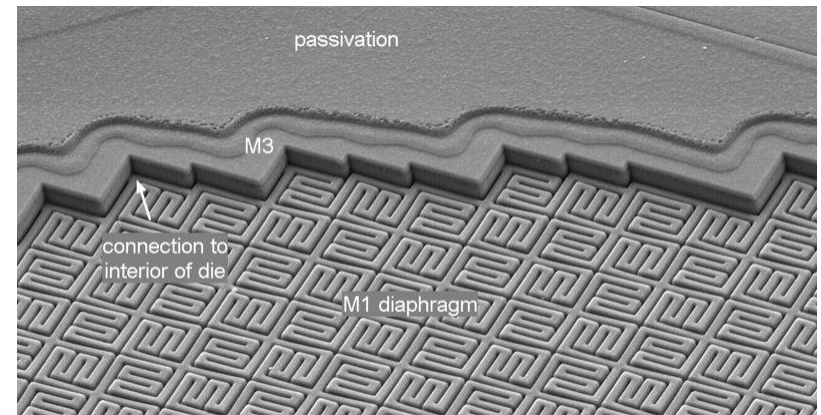
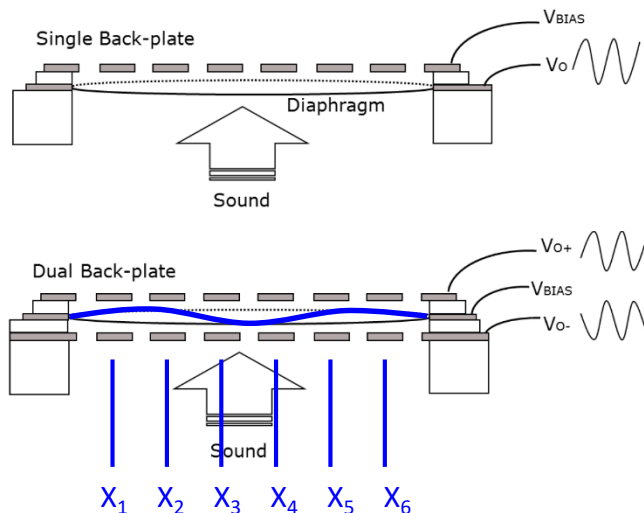
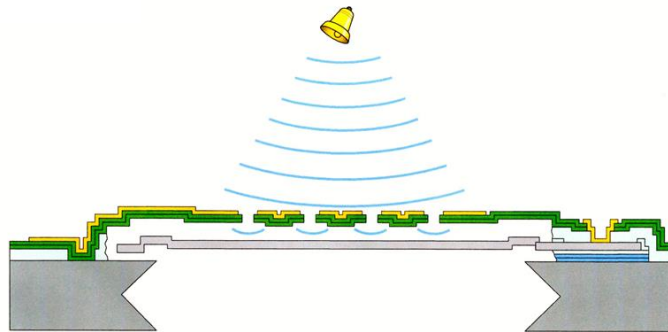
*higher frequencies can induce different membrane oscillations  
detection, however, says it is the basic frequency!*





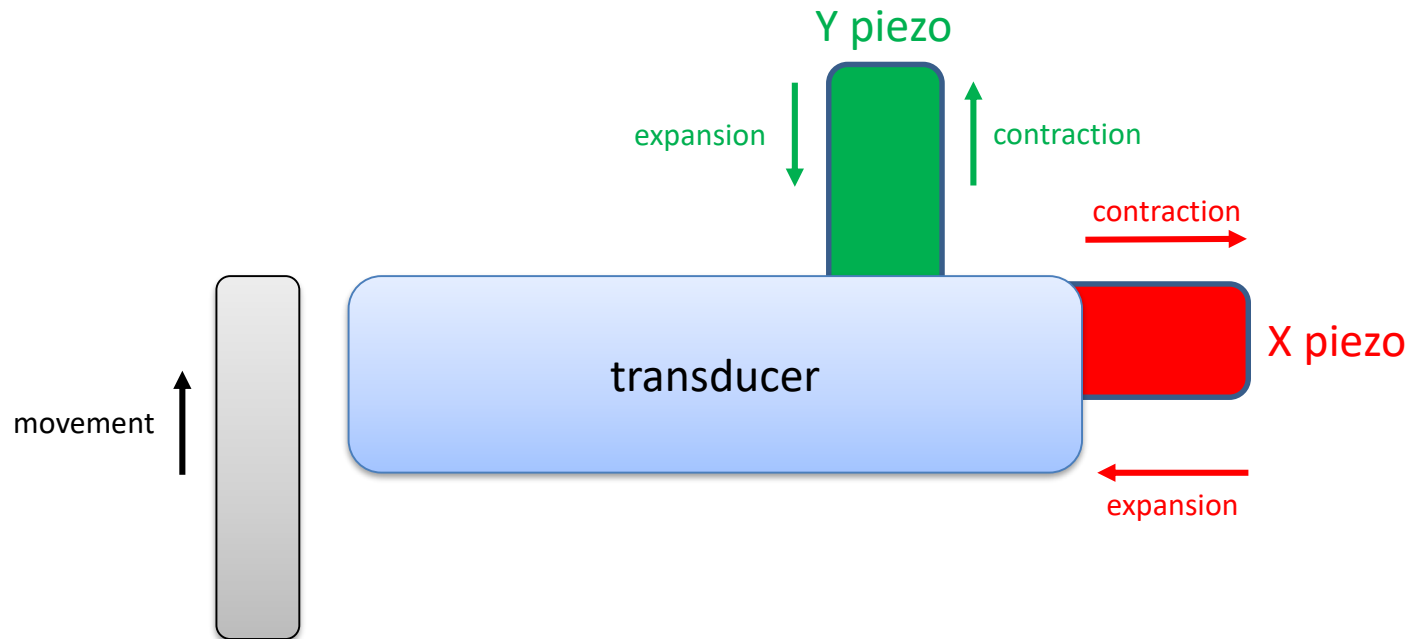
# Further Applications – MEMS Microphones

- Therefore, the **membrane** is used as **capacitive element** together with **perforated electrodes**
- This can be **improved by double face electrodes and / or by a smart electrode design**
- **Highly sophisticated systems** are also **double sided and position sensitive** to distinguish between basic frequencies and higher harmonics



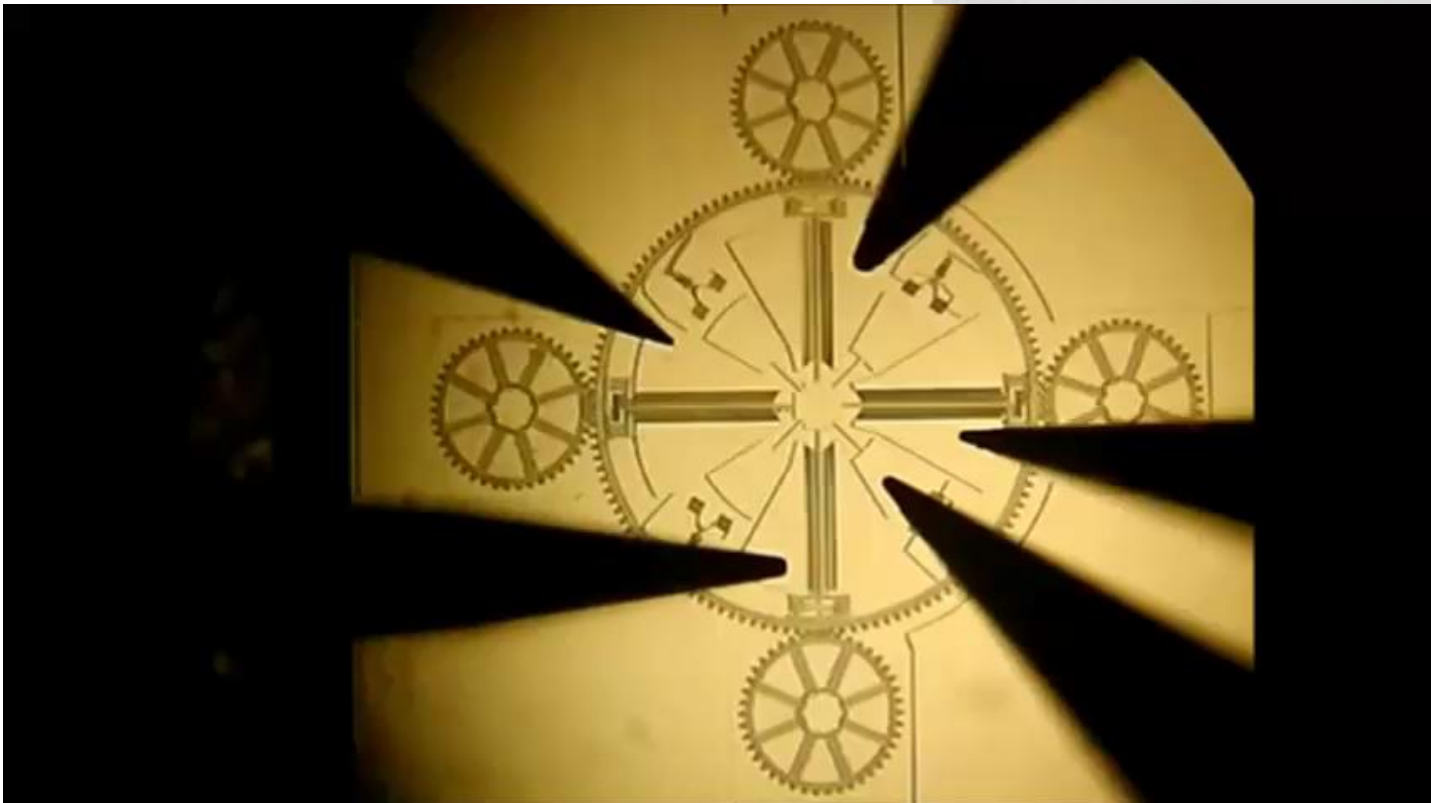
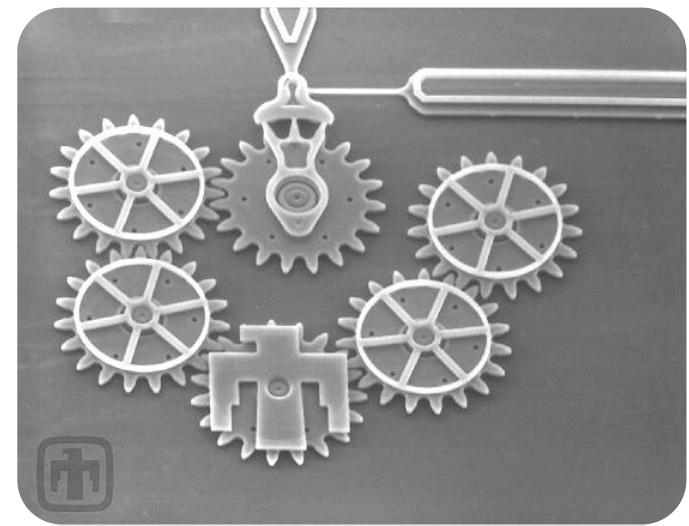
# Further Applications - Gears

- We have discussed the **surface micromachining of gear elements**
- The **movement bases on cyclic piezo control**



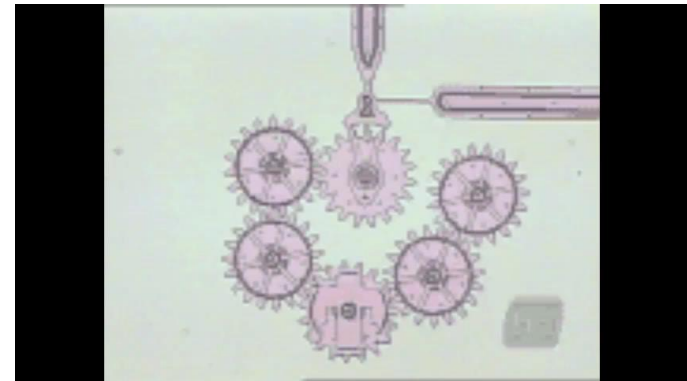
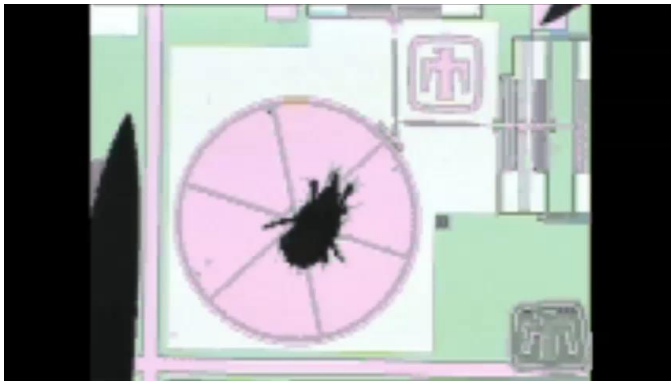
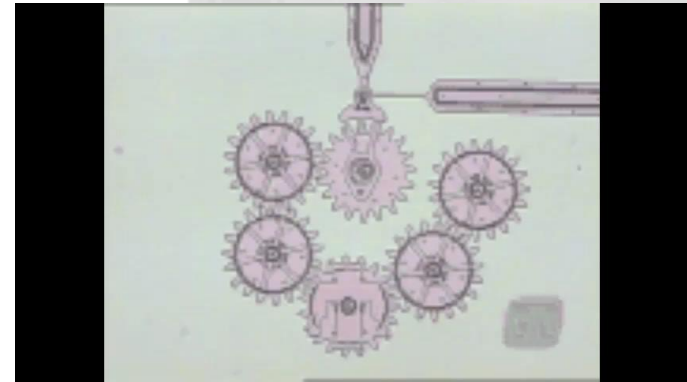
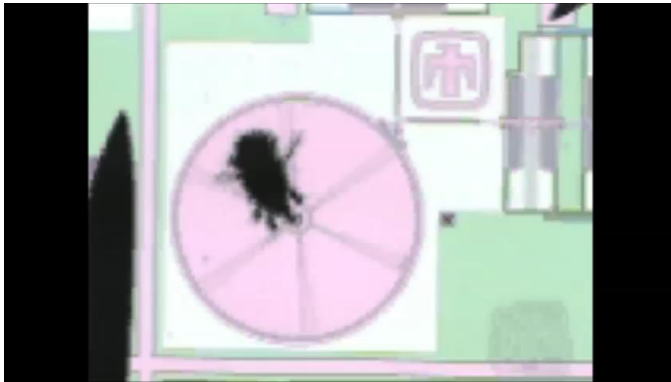
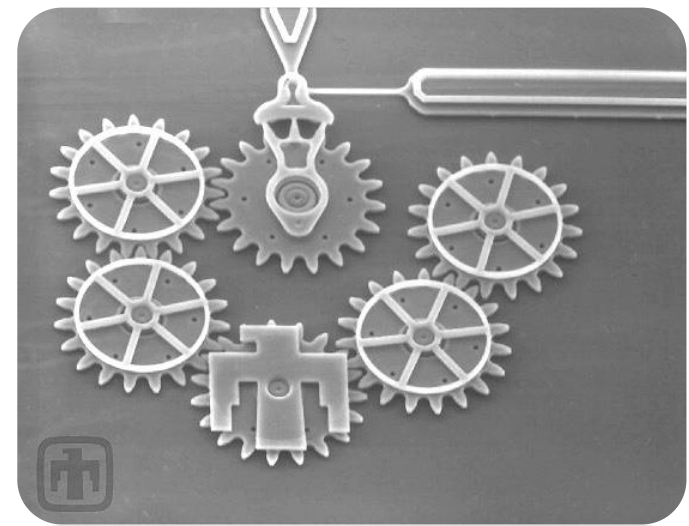
## Further Applications - Gears

- We have discussed the **surface micromachining of gear elements**
- The **movement bases on cyclic piezo control**
- Speeds of **more than 200.000 rpm (!) are possible!**



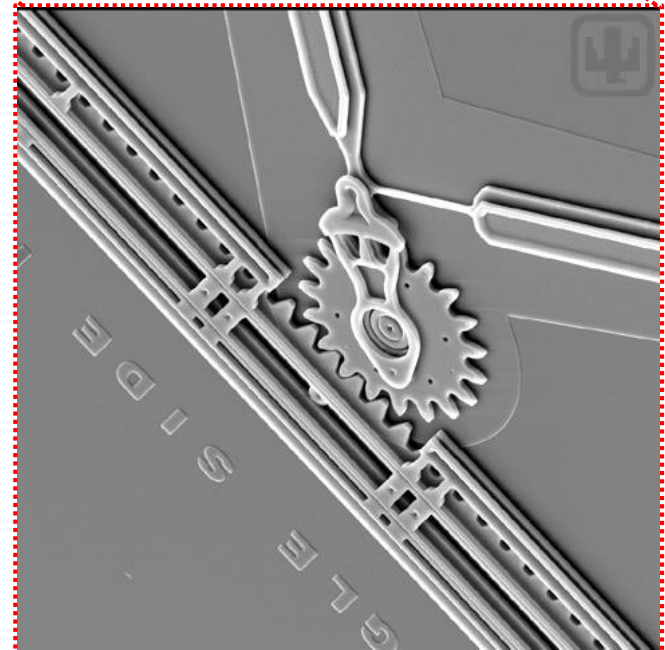
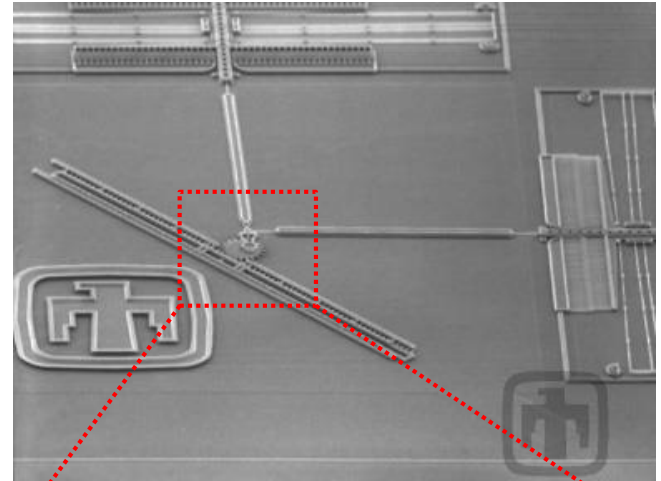
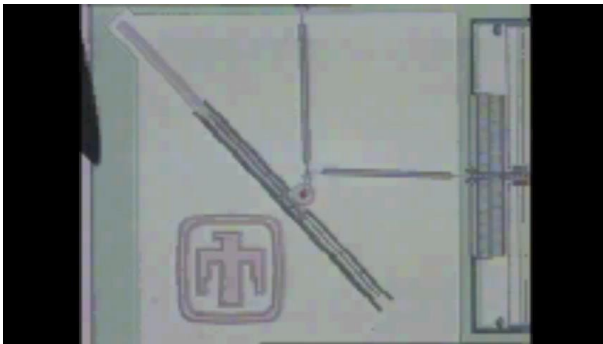
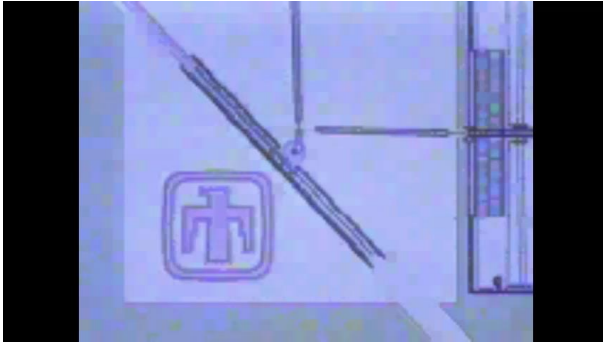
# Further Applications - Gears

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# Further Applications – Linear Motors

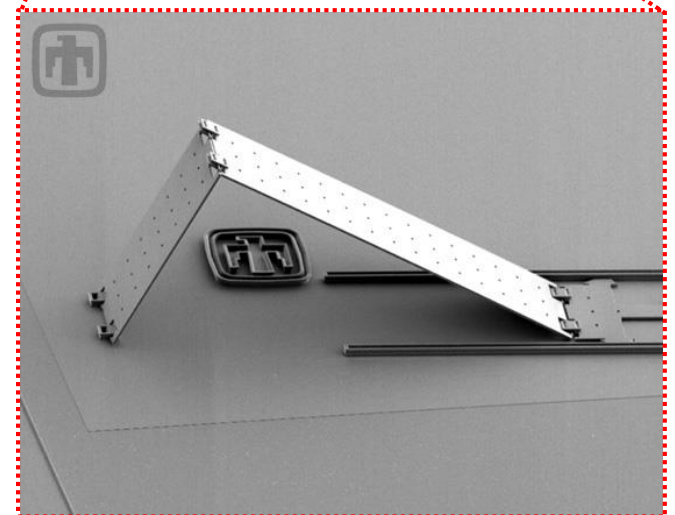
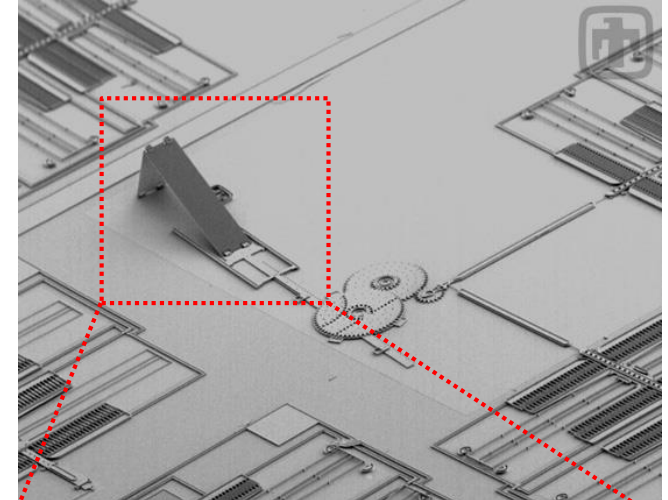
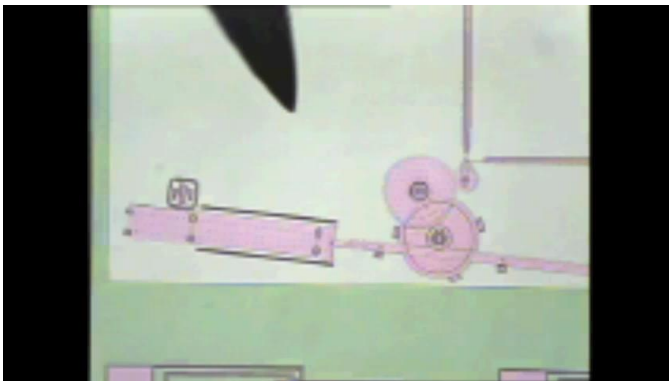
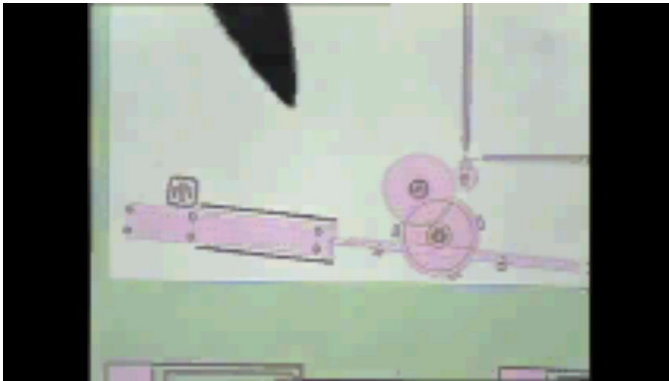
- Using the same drive principle, **linear motors can be done up to  $5 \text{ m}\cdot\text{s}^{-1}$ !**





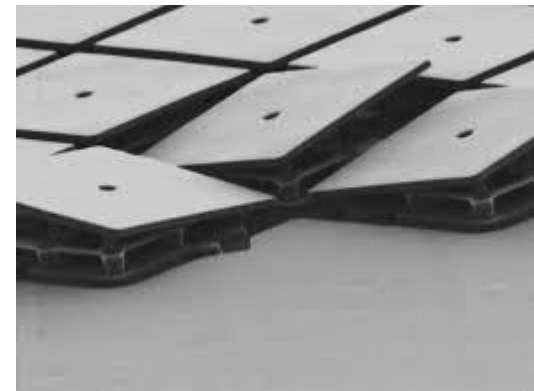
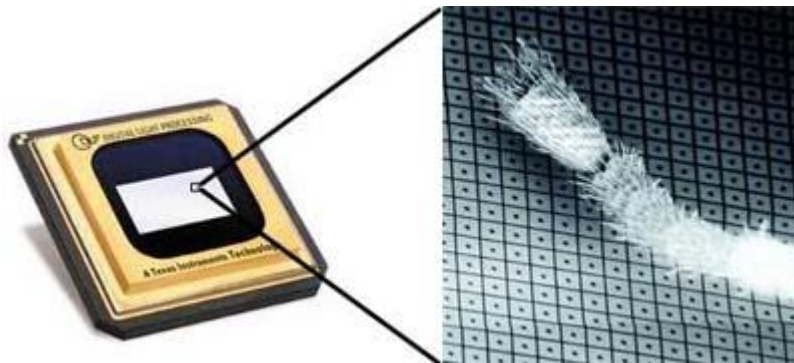
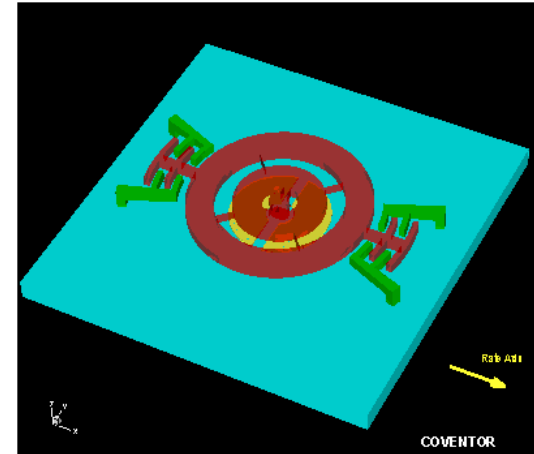
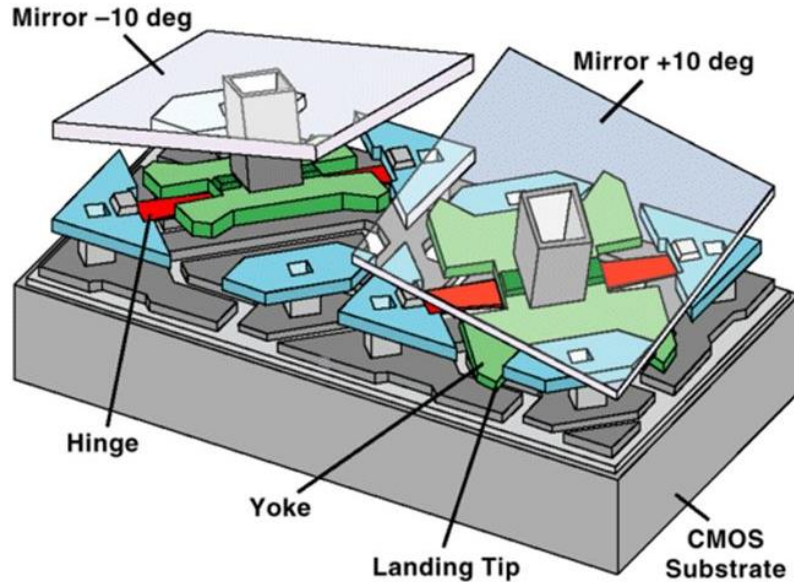
# Further Applications – Light Guidance / Manipulation

- Both concepts together can then be combined for the manipulation / guidance of light
- This is huge market in consumer applications such as projectors ... but how exactly?



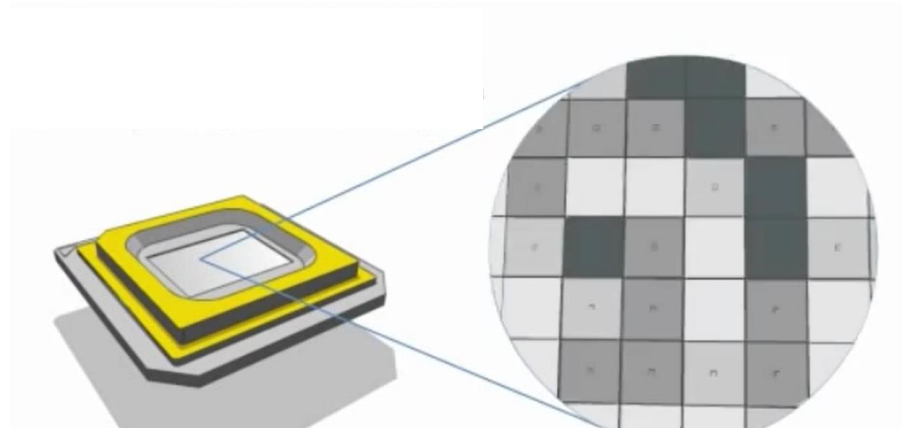
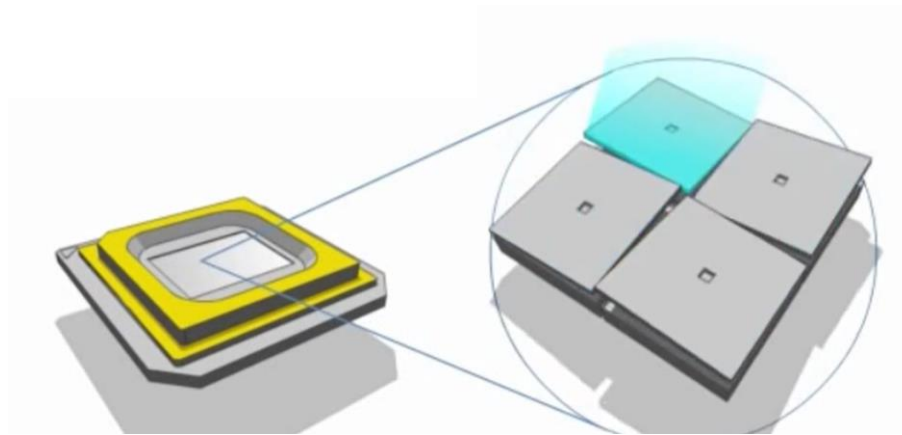
# Further Applications – Digital Light Processing (DLP)

- The base concept behind DLP are MEMS which allows highly precise positioning of a mirror then called Digital Micromirror Device (DMD)!



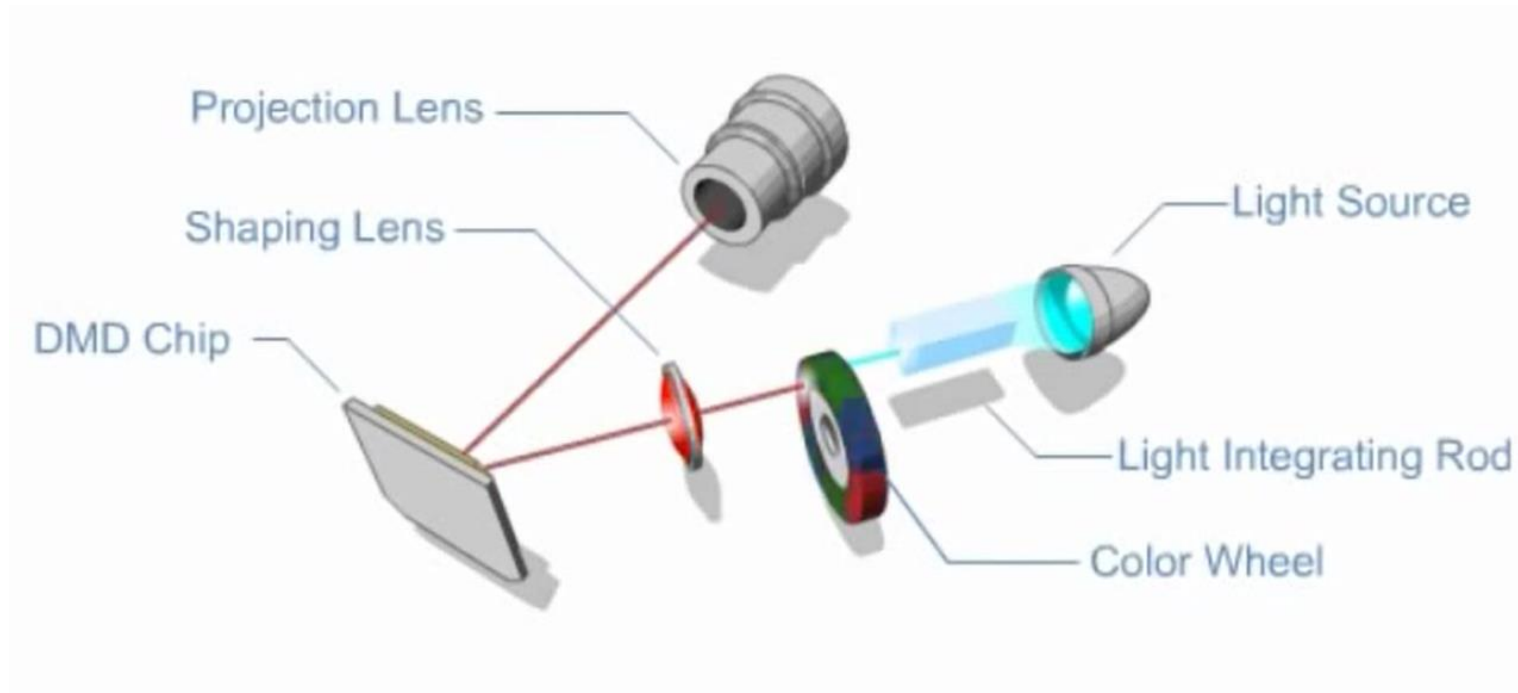
# Further Applications – Digital Light Processing (DLP)

- The full DMD technology **either reflects light into the final projector lens or away from it**
- By adjusting the **duration of ON – OFF**, typical **1024 intensity values** can be realized



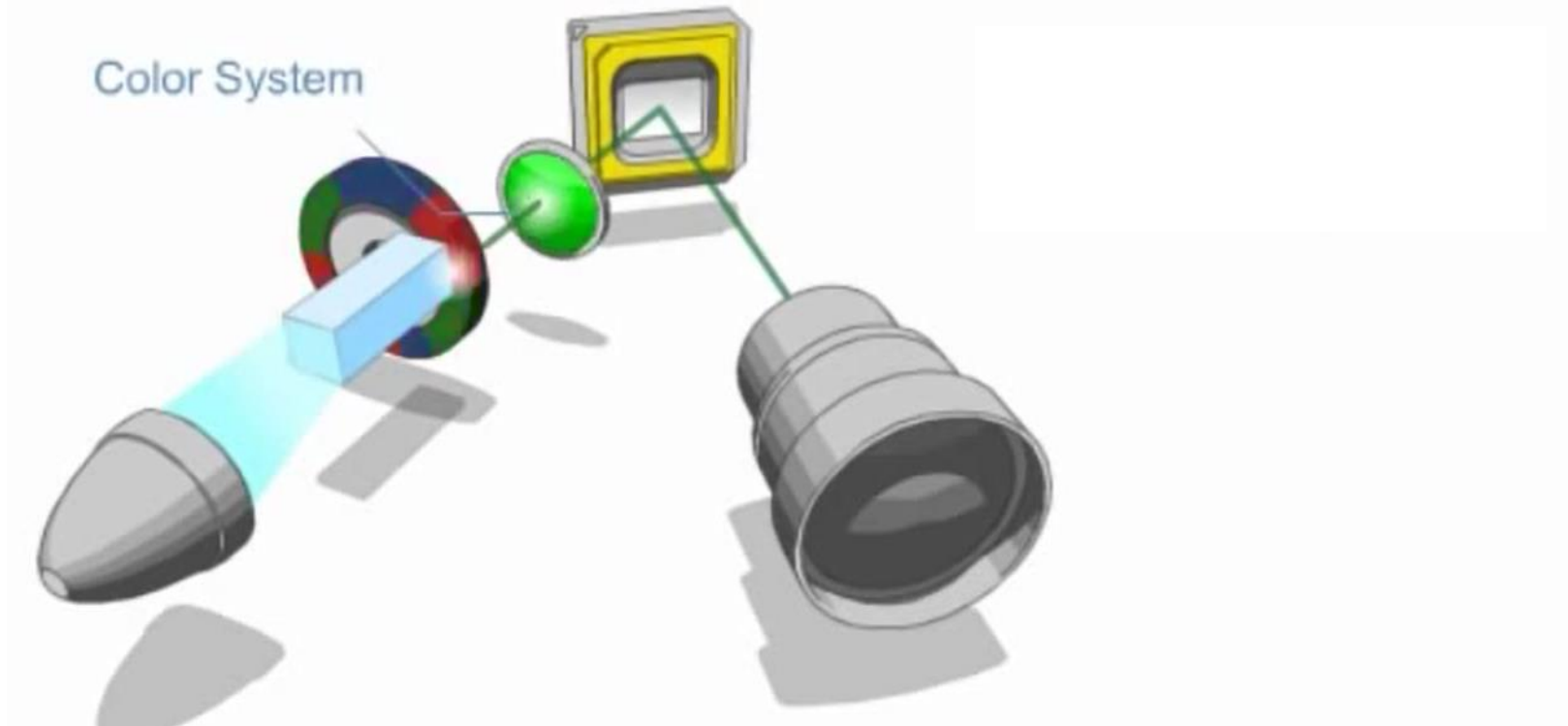
# Further Applications – Digital Light Processing (DLP)

- The **colour** comes into the game via a **colour wheel**, which **filters white light**
- By **synchronizing the colour wheel** with the **DMD elements**, a **RGB image can be created**
- The amazing detail is that such **DMD chips consist of the same numbers of mirrors as for the final resolution** up to 4k UHD (up to 4096×2160 pixels → more than 8.8 million mirrors!!!)



# Further Applications – Digital Light Processing (DLP)

- While [single-chip DLPs](#) still provide high performance, the trend goes towards [3-chip DLPs](#)

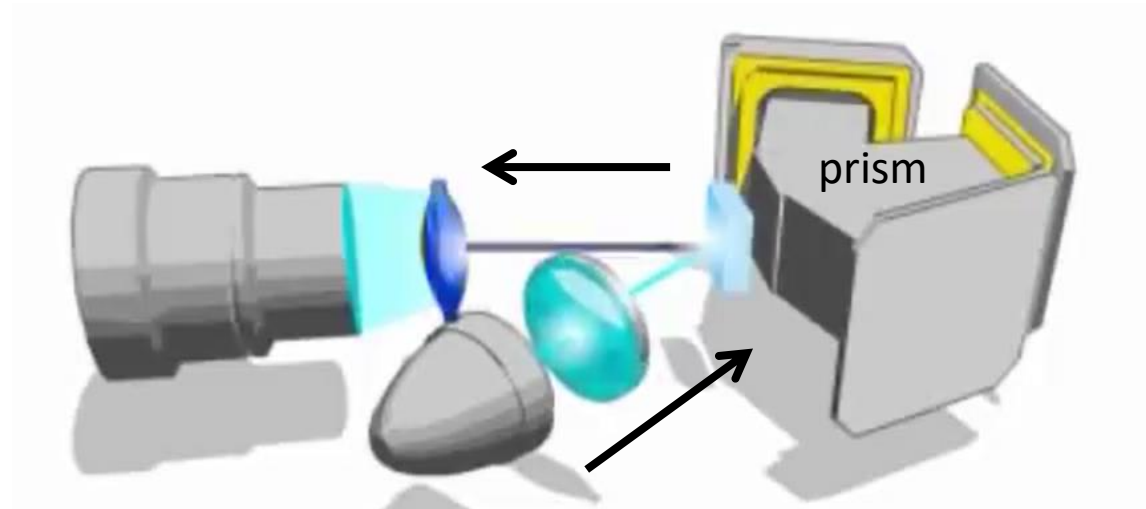






# Further Applications – Digital Light Processing (DLP)

- While **single-chip DLPs** still provide high performance, the trend goes **towards 3-chip DLPs**
- Here, **each DMD chip** is responsible for **ONE** single colour
- The setup uses **white light** which is then split up in **RGB colours** by a **prism**, guiding individual colours to the chip
- By that, the **brightness is much higher** as the colours are not timely split up!



# Further Applications – Digital Light Processing (DLP)

- Just for completeness, the 3-chip LCD technology uses no moving parts but large arrays of LCD elements which can switch the transmission for each pixel ON or OFF (but it is NOT a MEMS 😊)



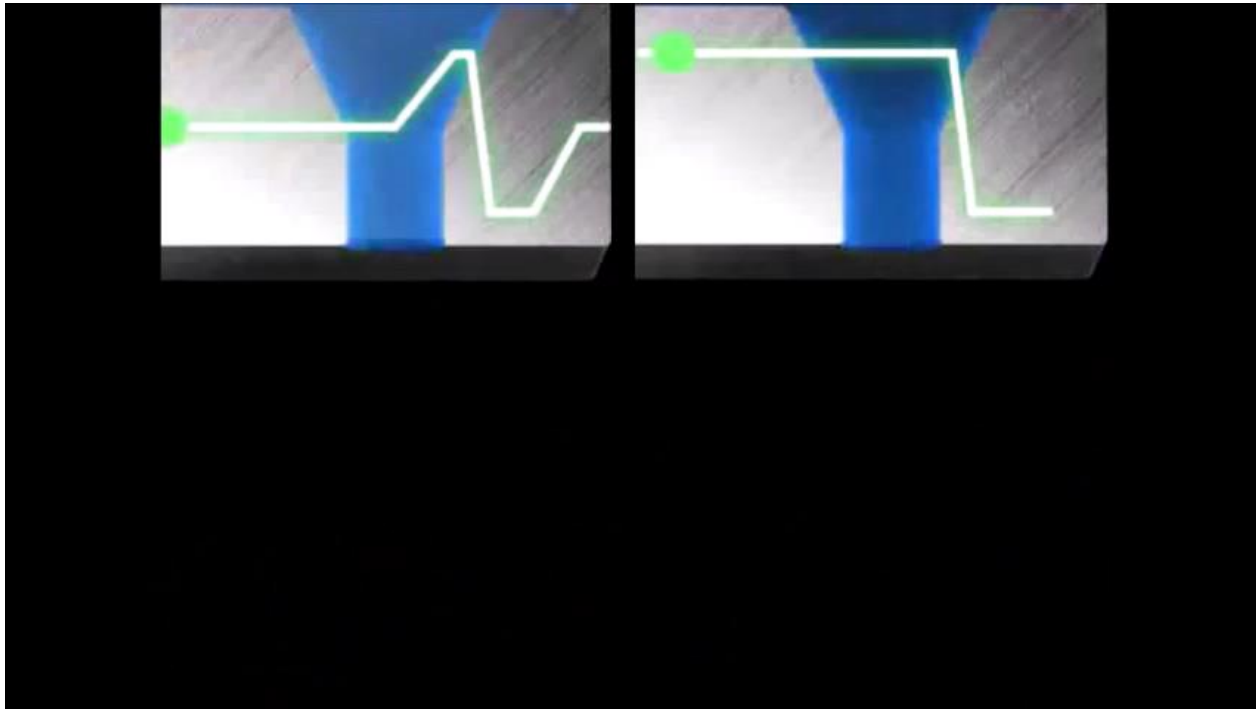
# Further Applications – Ink-Jet Printer

- Inkjet printing also bases on MEMS technology
- It increases / decreases the available volume at the nozzle end via piezoelectric elements



# Further Applications – InkJet Printer

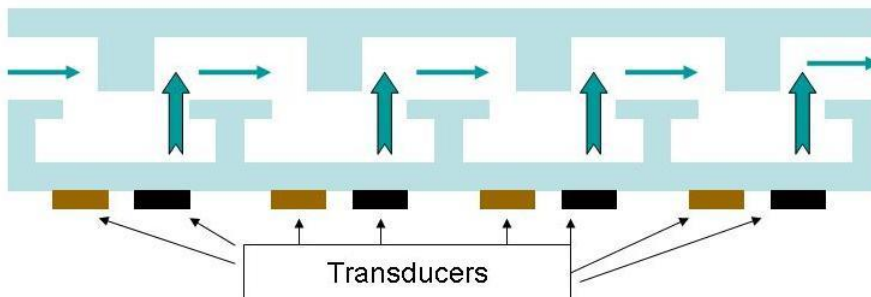
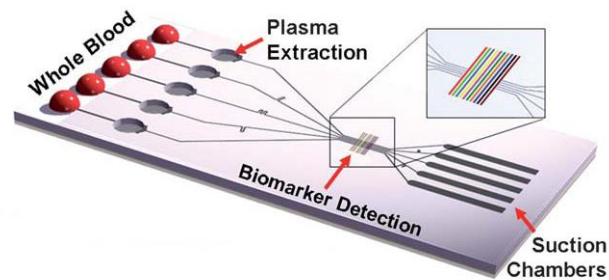
- However, **as it is fluid in motion** there are **post-ejection-movements** which **need to be taken into account for proper printing concerning droplet shapes and sizes**



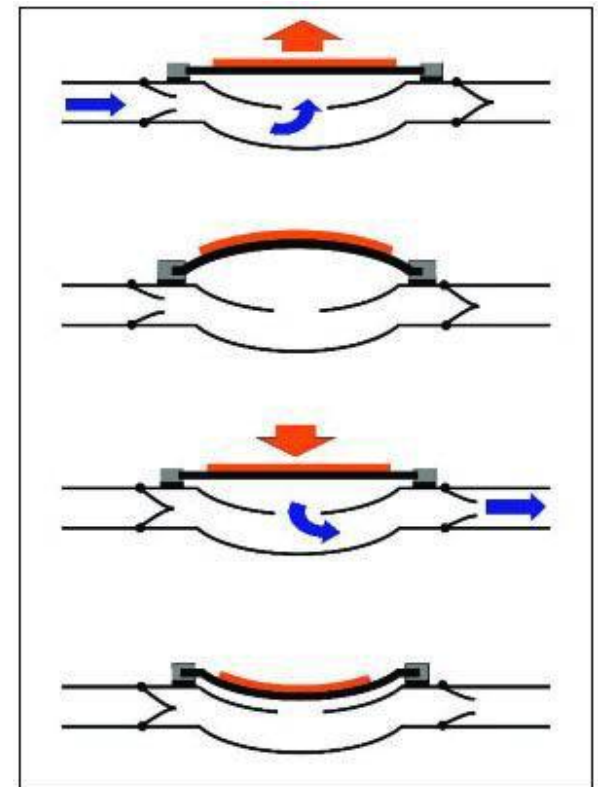


# Further Applications – Pumps for Microfluidics

- This basic concept can also be used for [Lab on a Chip applications](#) in e.g. life sciences
- [Multiple stacking](#) allows control of
  - ON – OFF
  - Flow rate
  - Directed fluid flow
  -

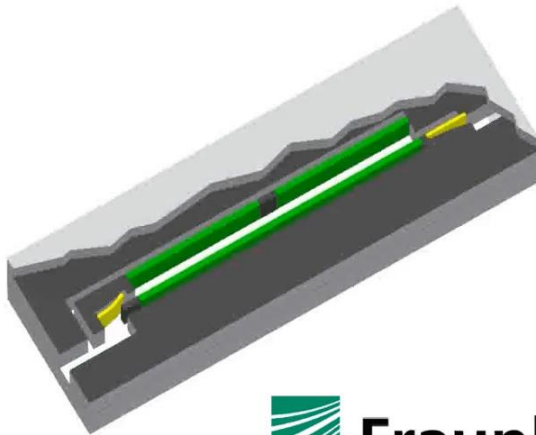
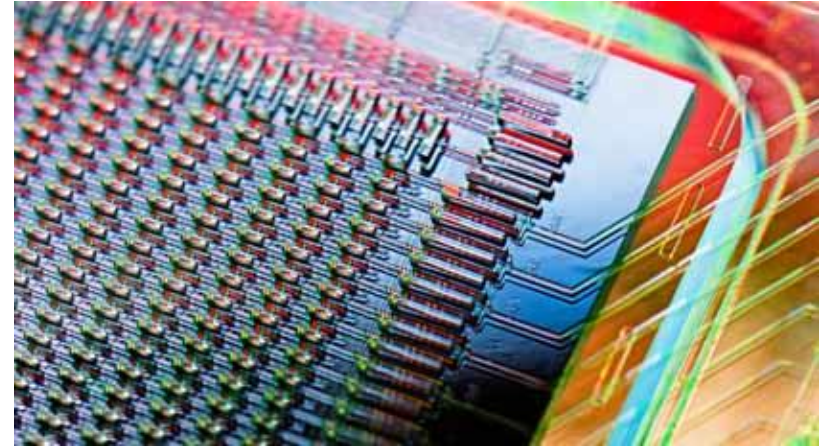


*unidirectional ON / OFF valve*

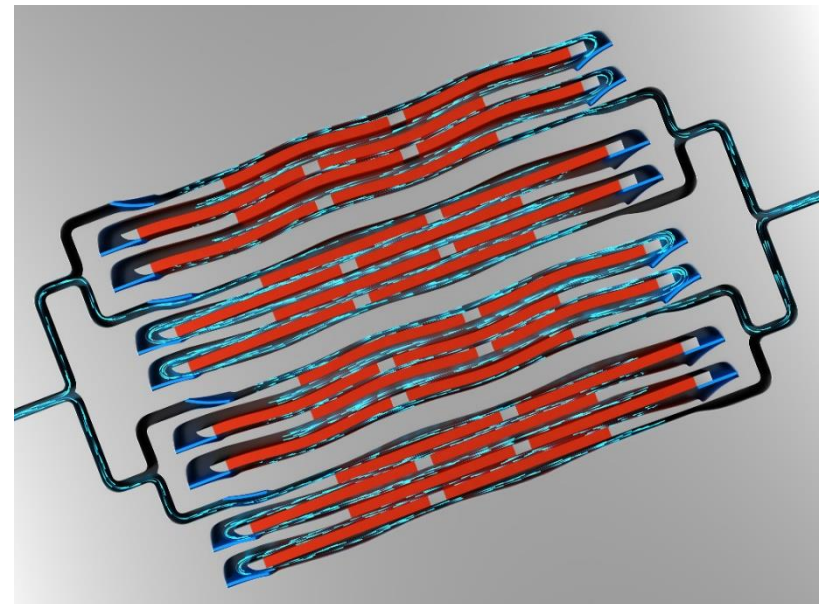


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- [Multiple stacking](#) allows control of
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  - Directed fluid flow
  - Mixing
  - Automated assays

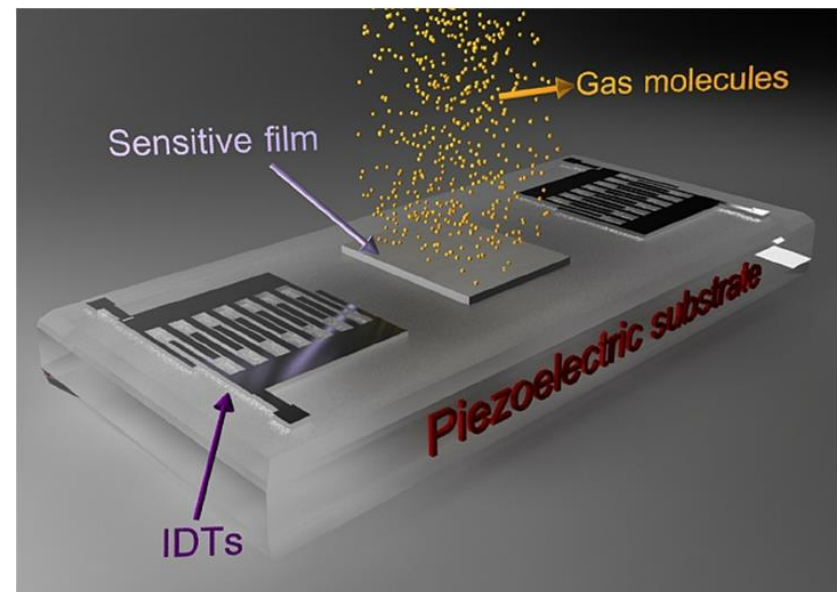
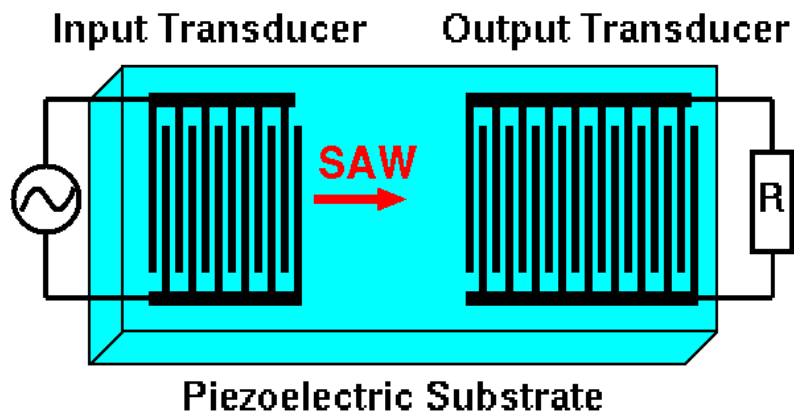


 **Fraunhofer**  
IPMS



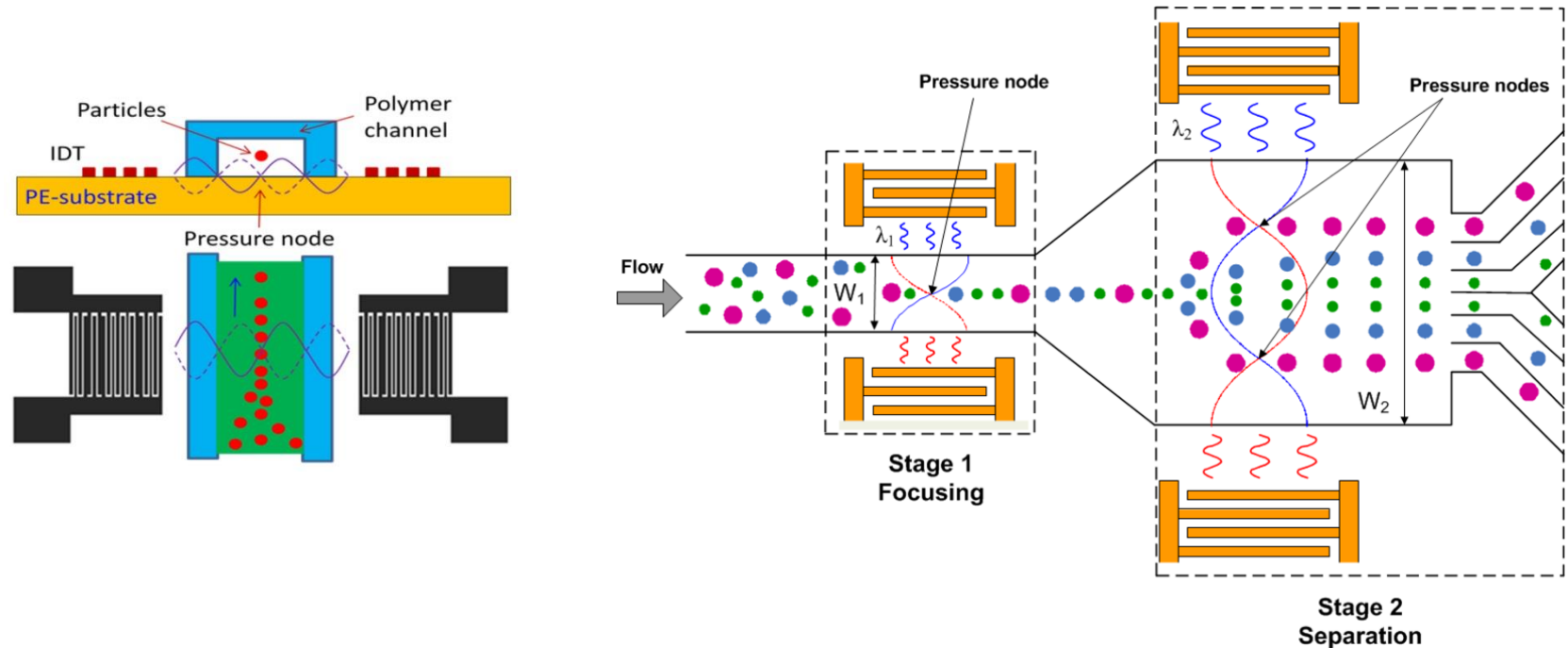
# Further Applications - SAW Devices

- Lab on a chip devices are often coupled with so called Surface Acoustic Wave (SAW) devices
- SAW devices use a piezoelectric material with two comb like structures
- When applying an AC signal at one side (Input) the piezoelectric material contracts / expands according to the electrode distance
- This induces a surface acoustic wave which propagates perpendicular to the electrodes
- On the other end, there are identical comb structures which act as sensor for the wave
- If there is a wave changing layer in between, the wave is changed by its amplitude / phase → **sensing!**



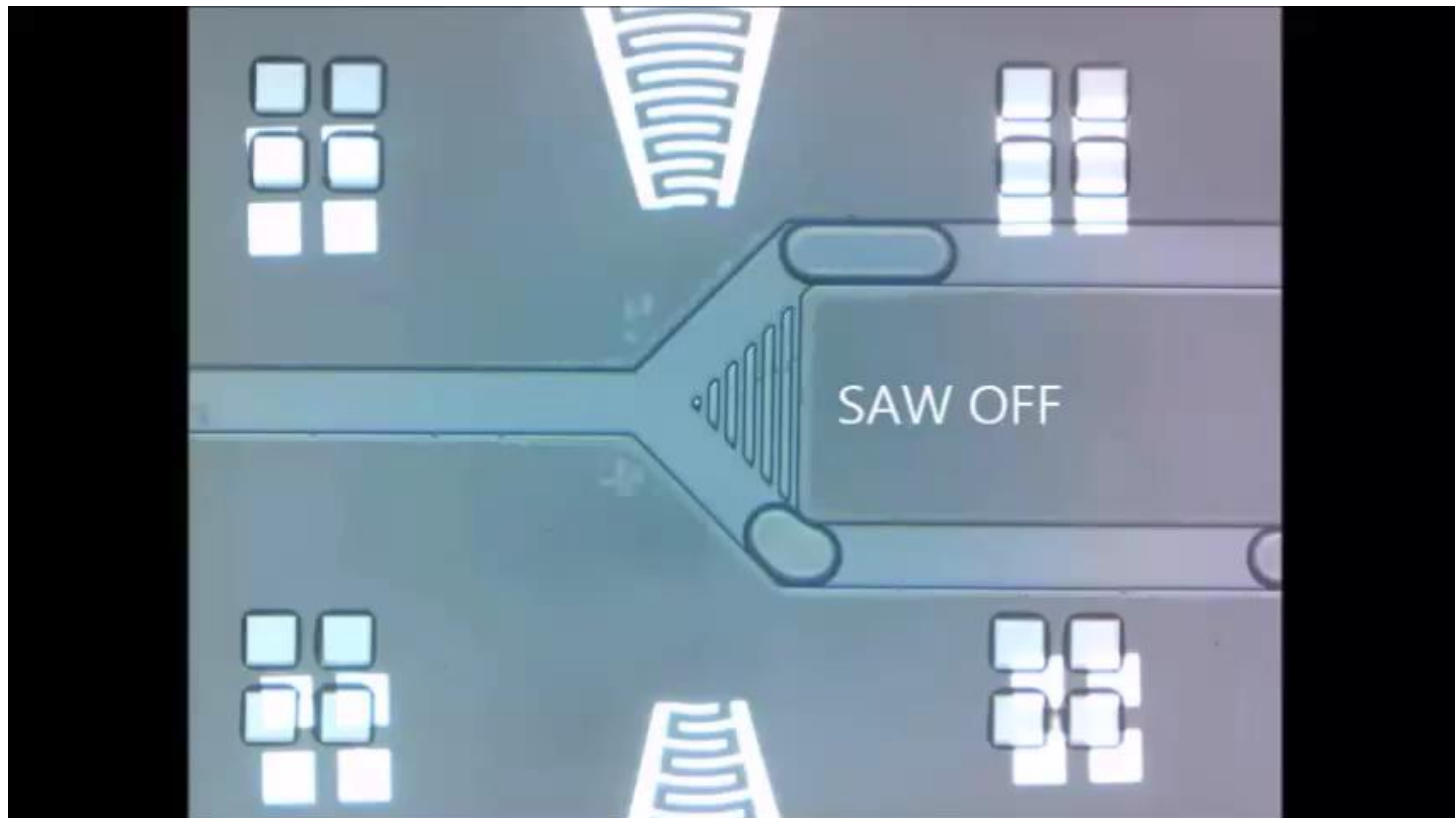
# Further Applications - SAW Devices

- By that, SAW devices can detect concentration variations in microfluidic channels without being in contact with the media (contact less MEMS sensors)
- An even more fancy application, however, is the fact that SAWs have spatial force gradients within the microfluidic channels
- By smart design, droplets and even single particles (!) can be FORCED on defined ways and even particle separation becomes possible!



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- By smart design, droplets and even single particles (!) can be FORCED on defined ways and even particle separation becomes possible!

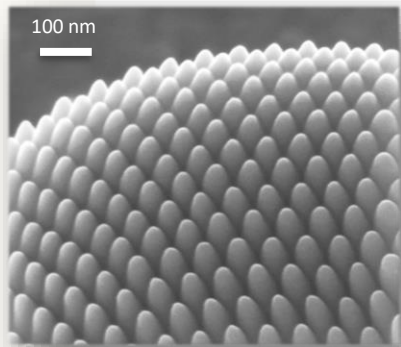




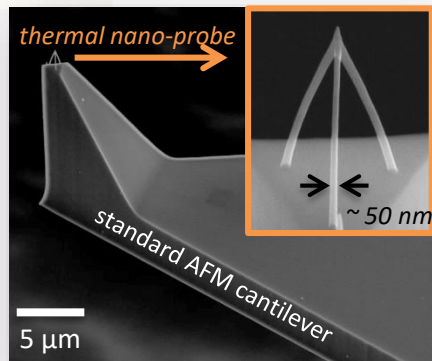
# Traditional Nanofabrication and its Limitations

- Traditional lithography approaches are **well established** and **widely used** in fundamental and applied physics
- **However, there are situations where they can not be applied!**

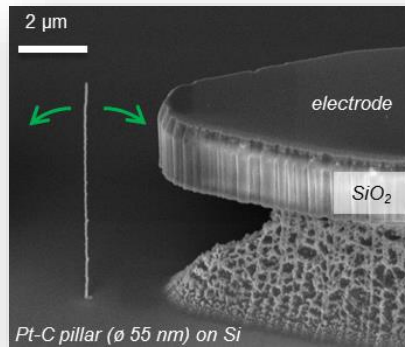
*additive light fiber modification*



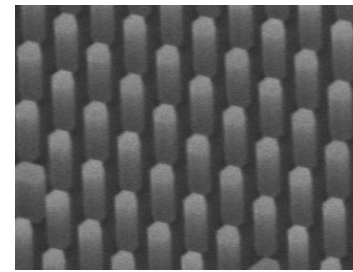
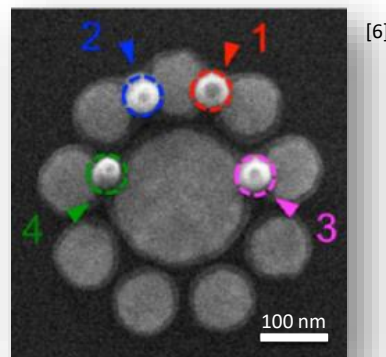
*highly exposed areas*



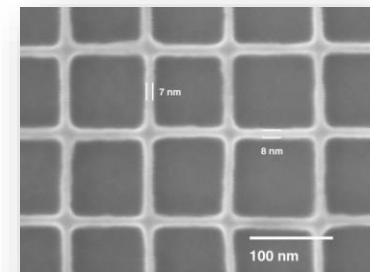
*on-demand fabrication*



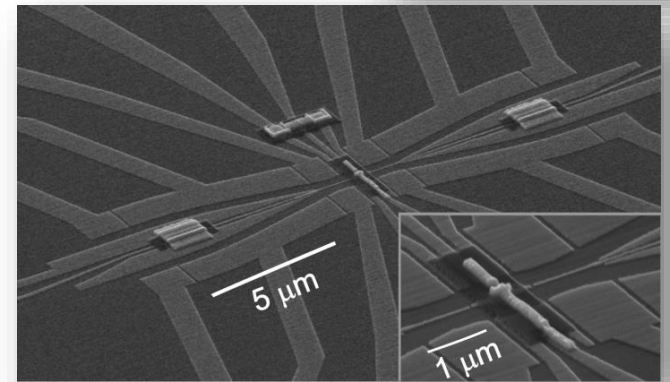
*plasmonic transmutation*



[4]

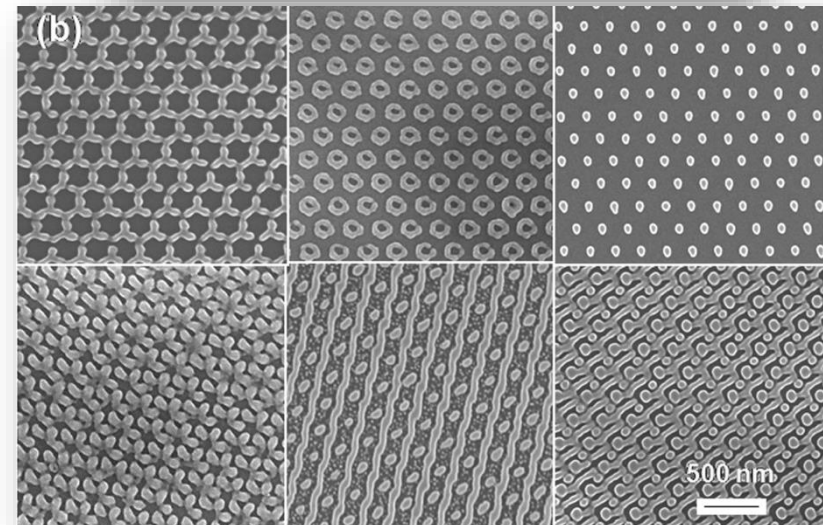


[3]



[1]

[2]

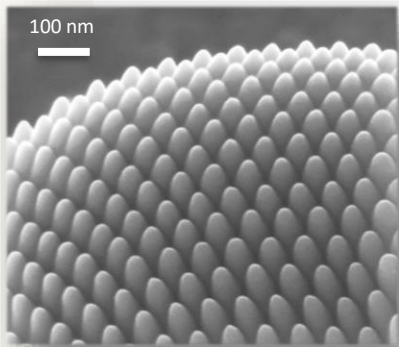




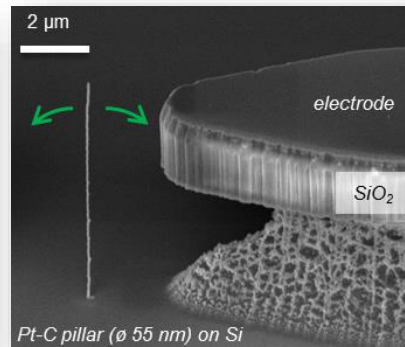
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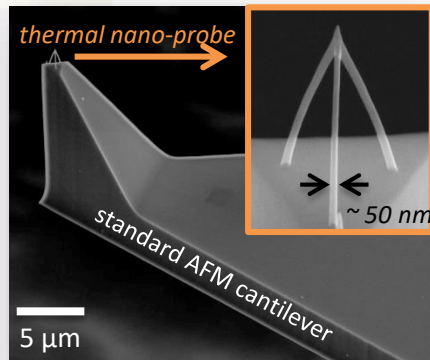
*additive light fiber modification*



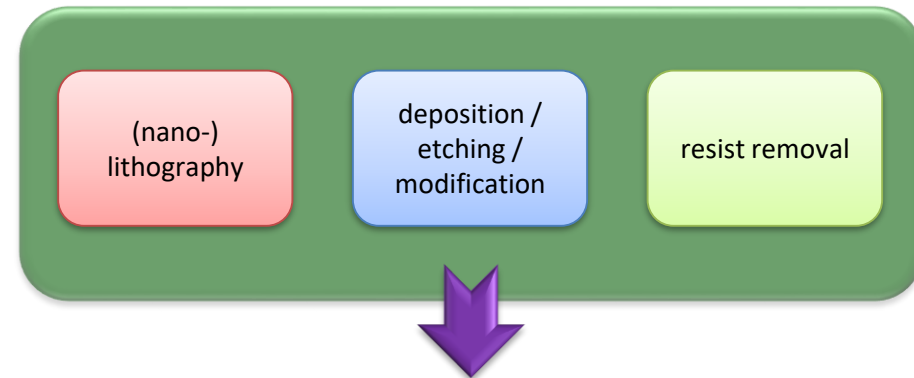
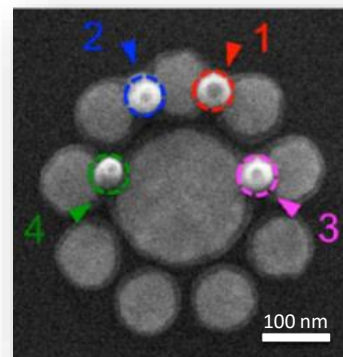
*on-demand fabrication*



*highly exposed areas*



*plasmonic transmutation*



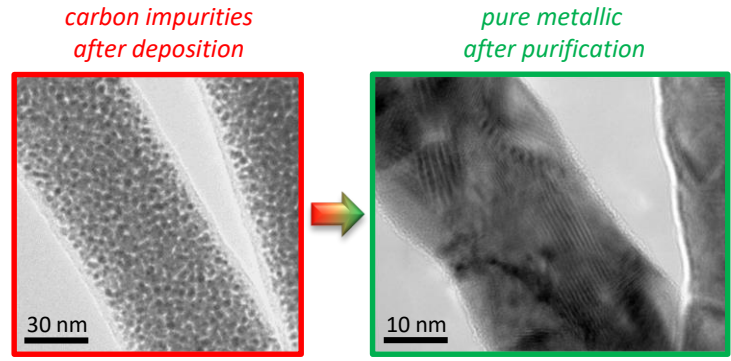
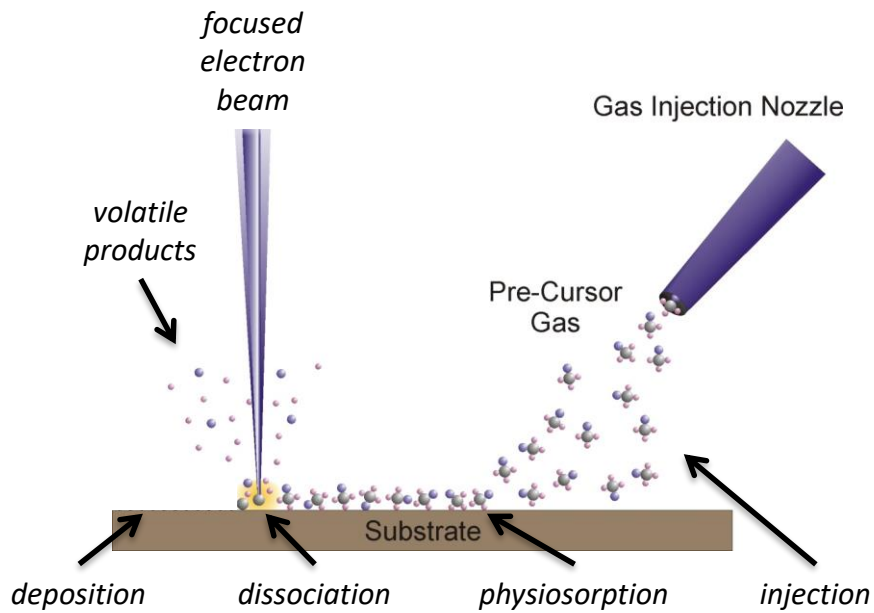
## **IDEAL Situation**

- **No additional layer** prior to fabrication
- **No masks** during lithography
- **No elevated temperatures** during processing
- **No reactive gases and / or liquids**
- **Minimally invasive** process conditions
- **3D capabilities**
- **Variable materials** capabilities
- **Complex shapes** apart from regular structures
- **Nanoscale capabilities**

Mask-less Direct-Write Fabrication

# Focused Electron Beam Induced Deposition (FEBID)

- FEBID is a very powerful method fabrication of functional nanostructures as it provides:
  - Mask-less, direct-write, bottom-up fabrication on virtually any given material / morphology
  - Different functionalities due to different precursor materials
  - Impurity free material properties
  - True 3D fabrication with spatial nanometer resolution

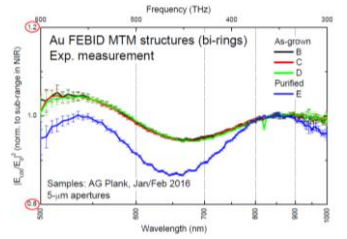
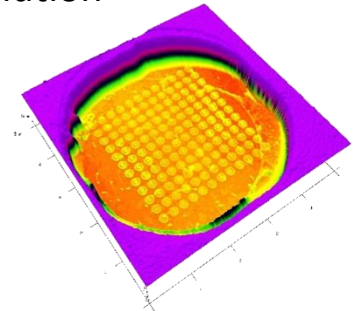


1																	2
H																	He
3	4											6	7	8	9	10	
Li	Be											B	C	N	O	F	Ne
11	12											13	14	15	16	17	18
Na	Mg											Al	Si	P	S	Cl	Ar
19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36
K	Ca	Sc	Ti	V	Cr	Mn	Fe	Co	Ni	Cu	Zn	Ga	Ge	As	Se	Br	Kr
37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54
Rb	Sr	Y	Zr	Nb	Mo	Tc	Ru	Rh	Pd	Ag	Cd	In	Sn	Sb	Te	I	Xe
55	56	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	
Cs	Ba	Hf	Ta	W	Re	Os	Ir	Pt	Au	Hg	Tl	Pb	Bi	Po	At	Rn	
87	88	104	105	106	107	108	109	110	111	112	113	114	115	116	117	118	
Fr	Ra	Rf	Db	Sg	Bh	Hs	Mt	Ds	Rg	Cn	Uut	Fl	Uup	Lv	Uus	Uuo	

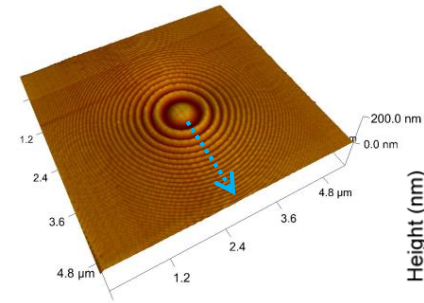
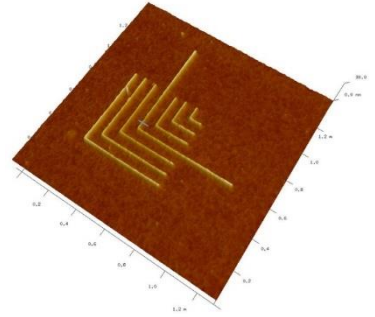
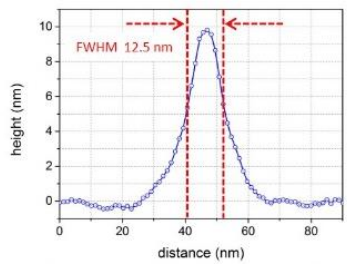
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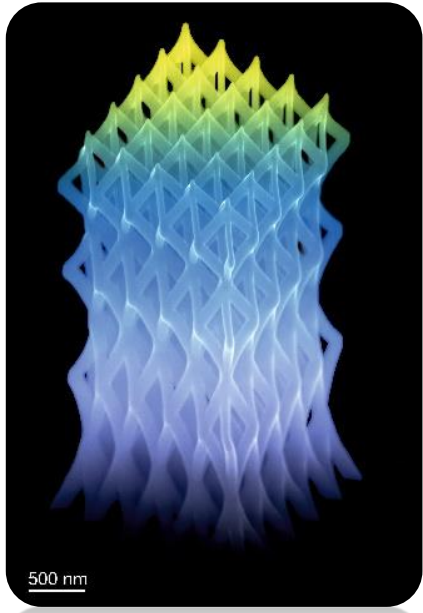
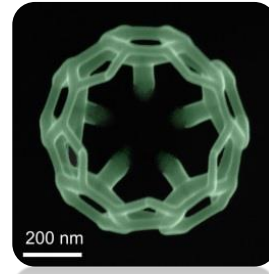
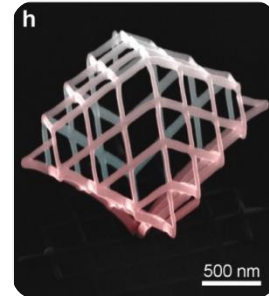
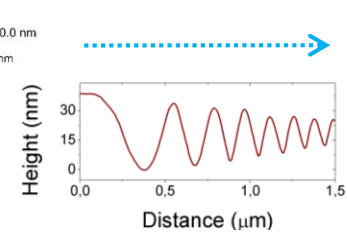
plasmonic light manipulation



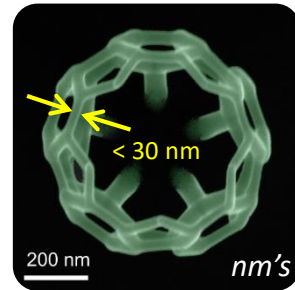
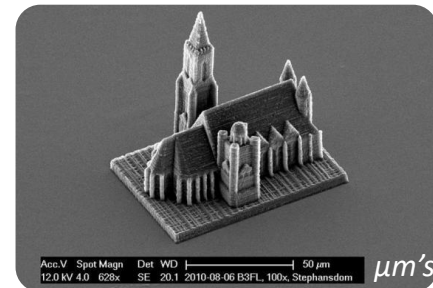
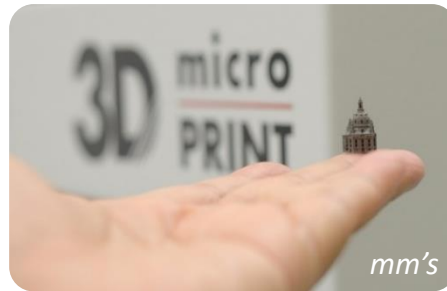
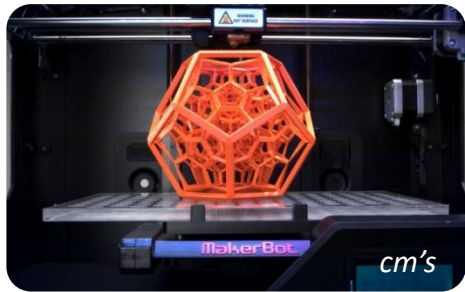
high-resolution fabrication



fully sine modulated Gabor lens



# A Novel Approach for True 3D Nanoprinting



By this, our technology expands the pool of **true 3D Nano-Printing to the real nanoscale with essential advantages**

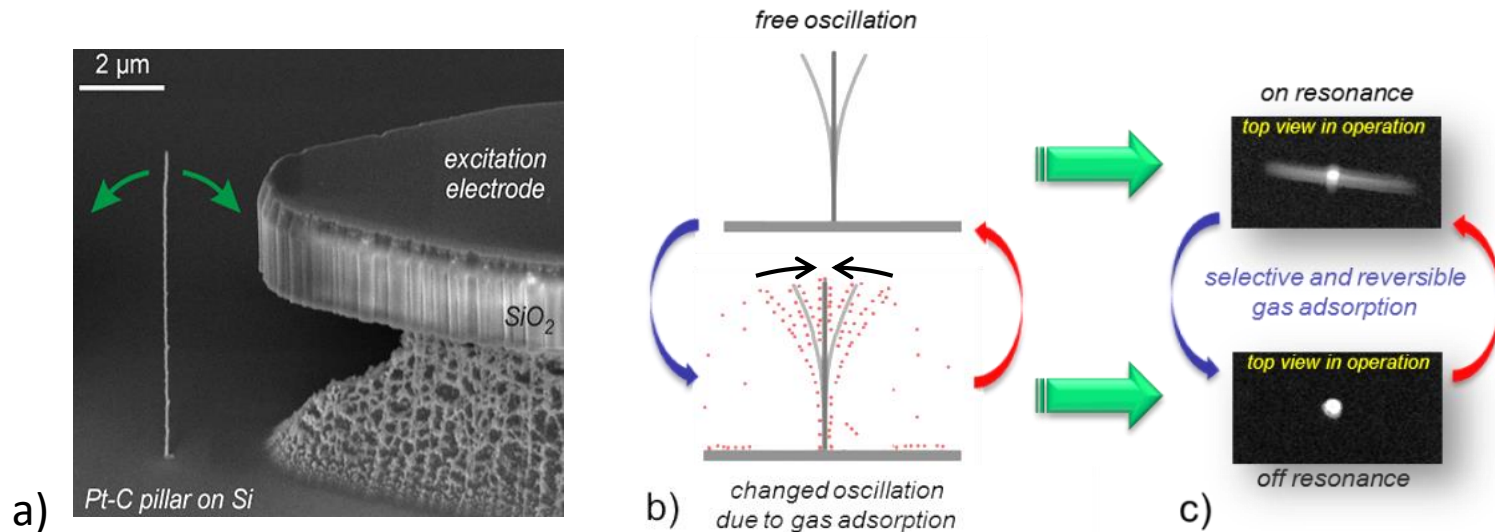
- Minimally invasive direct-write, bottom-up fabrication on almost any substrate material / surface
- Highly precise fabrication of multi-dimensional, functional nanostructures ...
- ... with the unique strength of true 3D nano-fabrication

FEBID 3D Nanoprinting can be seen as **generic technology** for

- research → e.g. fundamental studies in optics, mechanics or sensing
- development → e.g. functional nano-probes / sensors with industry

# Applications: Quasi-1D Gas / Mass Sensing

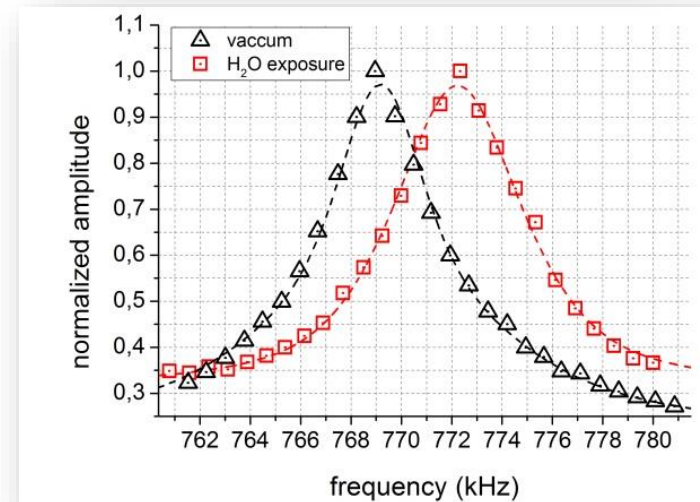
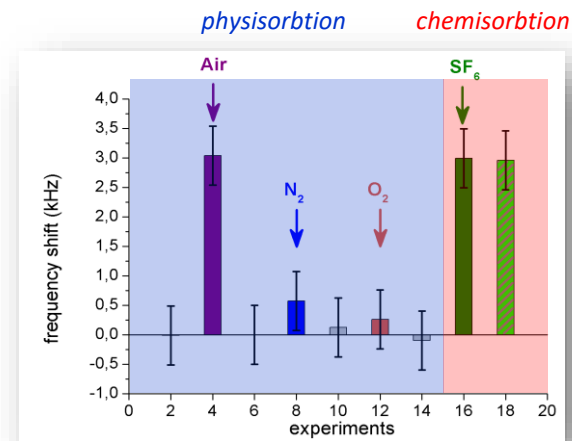
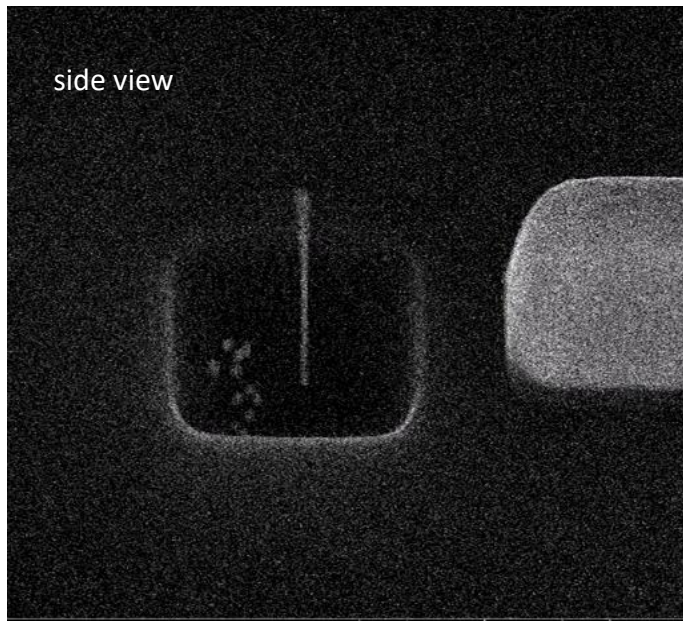
- Quasi-1D Pt-C nano-pillars can be excited via electric AC-fields according to their mechanical resonance frequency
- Once, the diameter and / or the mechanical properties are changed by physical / chemical adsorption from the gas phase, the resonance shifts accordingly





# Applications: Quasi-1D Gas / Mass Sensing

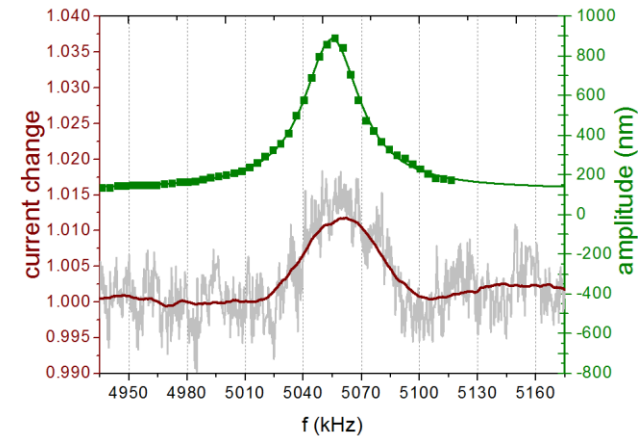
- The **small dimensions** and the **soft mechanical character** allow **highly sensitive**
  - **gas sensing** (reversible)
  - **mass sensing** (irreversible)
  - **Detection limit in the lower Attogram range**



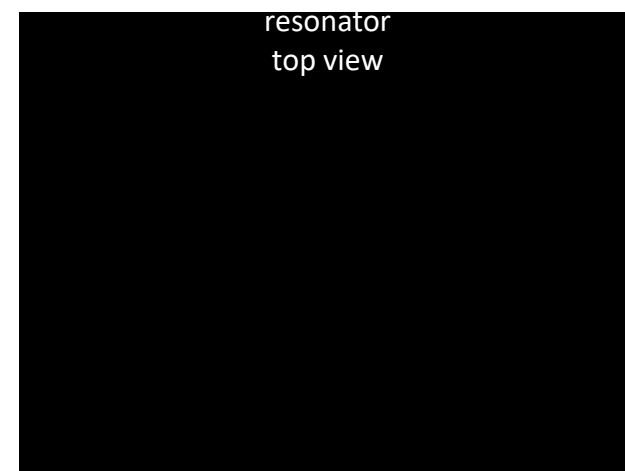
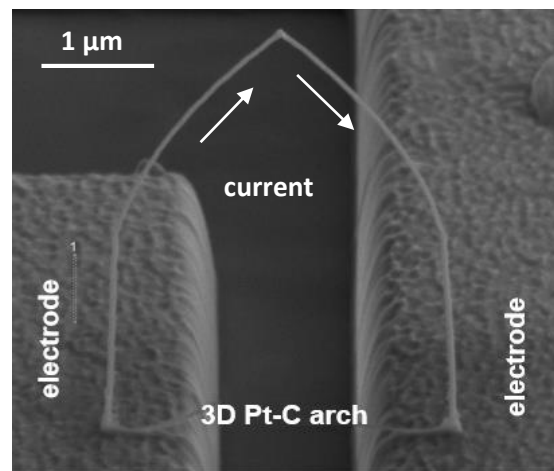
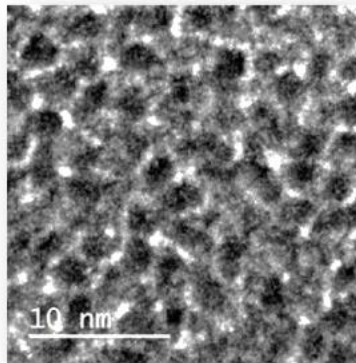


# Applications: Quasi-1D Gas / Mass Sensing

- This basic principle is then **expanded** by the **unique material properties** of FEBID materials
- As they consist by **~ 2 nm large metal crystals embedded in an insulating carbon matrix**, the **electric transport** is determined by **tunneling processes**
- **Once the structure is bended**, the **particles get closer**, the **tunneling probability increases** leading to **higher conductivity!**
- *That can be used for simple electric detection!*



~ 2 nm metal particle in polymer



## Future Applications – 3D Nano-Manipulators

- As we now have the technology under control, further steps goes towards nano-manipulation such as tweezers or optical filter systems ...

